# On a Problem of Bremermann Concerning Runge Domains \*

Cezar Joita

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#### Abstract

In this paper we give an example of a bounded Stein domain in  $\mathbb{C}^n$ , with smooth boundary, which is not Runge and whose intersection with every complex line is simply connected.

### 1 Introduction

In [2] Bremermann asked the following question:

"Suppose that D is a Stein domain in  $\mathbb{C}^n$  such that for every complex line l in  $\mathbb{C}^n$ ,  $l \setminus D$  is connected. Is it true that D is Runge in  $\mathbb{C}^n$ ?"

The question remained open and was mentioned again in a recent book by T. Ohsawa ([5], page 81). In this paper we will give a negative answer to Bremermann's question. Namely, we will give an example of a bounded, strictly pseudoconvex domain in  $\mathbb{C}^n$  with real analytic boundary which is not Runge in  $\mathbb{C}^n$  but whose intersection with every complex line is simply connected.

Note that if D is bounded the hypothesis of the problem means simply that for every complex line  $l, l \cap D$  is Runge in l. If, in addition, one requires that  $l \cap D$  is connected as well then it does follow that D is Runge. See for example [1], page 79, Theorem 3.1.5 or [3], page 309, Theorem 4.7.8.

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For simplicity our construction will be done in  $\mathbb{C}^2$  but it can be easily adapted to  $\mathbb{C}^n$  for  $n \geq 2$ . To produce our example we will construct first a bounded, strictly pseudoconvex domain  $W \subset \mathbb{C}^2$  with smooth, real analytic boundary which is Runge but its closure is not holomorphically convex. (Note that this is not possible in  $\mathbb{C}$ .) Next we show that, in fact, we can construct W as above and moreover it has the following geometric property: for every complex line l the set of points where l is tangent to  $\partial W$  is at most finite. If this is the case, then one can show that  $l \cap \overline{W}$  is polynomially convex, again for every complex line l. Finally, we show that an appropriate neighborhood of  $\overline{W}$  is a counterexample to Bremermann's problem.

## 2 The Example

The construction will be done in several steps.

First we prove that there exists a bounded domain in  $\mathbb{C}^2$  with smooth, real analytic boundary which is strictly pseudoconvex, Runge in  $\mathbb{C}^2$ , and its closure is not polynomially convex. To our knowledge, such an example does not exist in the literature.

J. Wermer [6] proved that there exists a biholomorphic map F from a polydisc  $P=\{(z_1,z_2)\in\mathbb{C}^2: |z_1|< a, |z_2|< b\}$  in  $\mathbb{C}^2$  onto an open set F(P) of  $\mathbb{C}^2$  such that F(P) is not polynomially convex. (Wermer's original result was in  $\mathbb{C}^3$  but it can be modified to hold in  $\mathbb{C}^2$  as well; see [4] or [5].) We start with such a map and let  $U_n:=\{z\in\mathbb{C}^2: |\frac{z_1}{a}|^n+|\frac{z_2}{b}|^n<1\}$ . Since  $U_n\subset U_{n+1}\subset P$  and  $\cup U_n=P$ , it follows that there exists  $m\in\mathbb{N}$  such that  $F(U_m)$  is not polynomially convex. Set  $U=U_m$  and V=F(U). If we define  $\varphi:U\to\mathbb{R}$  by  $\varphi(z)=\frac{1}{1-|z_1/a|^{2m}-|z_2/b|^{2m}}+|\frac{z_1}{a}|^2+|\frac{z_2}{b}|^2-1$  then  $\varphi$  is a strictly plurisubharmonic real analytic function and has only one critical point. Since F is a biholomorphism,  $\varphi\circ F^{-1}:V\to\mathbb{R}$  has the same properties and it is an exhaustion function for V. For  $\alpha>0$  let  $V_\alpha=\{z\in V: \varphi\circ F^{-1}(z)<\alpha\}$ . It follows that there exists  $\alpha>0$  such that  $V_\alpha$  is not polynomially convex. On the other hand, if  $z_0=F(0)$  (this is the minimum point and the only critical point of  $\varphi\circ F^{-1}$  and  $\varphi\circ F^{-1}(z_0)=0$ ) and we choose  $B\subset V$  a ball centered at  $z_0$ , then there exists  $\alpha>0$  such that  $V_\alpha\subset B$ . It follows that  $V_\alpha$  is Runge in B (because  $\varphi\circ F^{-1}$  is defined on B) and therefore is polynomially convex. Put  $r:=\sup\{\alpha\in\mathbb{R}: V_\alpha \text{ is polynomially convex}\}$ . From the above observations we deduce that  $0< r<\infty$ .

We claim that  $V_r$  is the example that we are looking for. Indeed  $V_r$  is Runge in  $\mathbb{C}^2$  as an increasing union of Runge domains and it has smooth, real analytic boundary because  $\varphi \circ F^{-1}$  has no critical point on the  $\partial V_r$ . We only need to convince ourselves that  $\overline{V}_r = \{z \in V : \varphi \circ F^{-1}(z) \leq r\}$  is not polynomially convex. If  $\overline{V}_r$  were polynomially convex then it would have a Runge (in  $\mathbb{C}^2$ ) neighborhood W with  $W \subset V$ . If this were the case then for  $\epsilon > 0$  small enough, we would have  $V_{r+\epsilon} \subset W$  and  $V_{r+\epsilon}$  would be Runge in W and therefore in  $\mathbb{C}^2$ . This would contradict the choice of r.

Let us rephrase what we have done so far. We proved that if V is a domain in  $\mathbb{C}^2$  and  $\phi: V \to \mathbb{R}$  is a strictly plurisubharmonic function such that there exist  $a_0 < a_1$  real numbers with the following properties:

$$\begin{cases} x \in V : \phi(x) < a_1 \} \subset \subset V, \\ \{x \in V : \phi(x) < a_0 \} \text{ is connected and contains } C(\phi) := \text{the set of critical points of } \phi, \\ \{x \in V : \phi(x) < a'\} \text{ is Runge in } \mathbb{C}^2, \text{ for some } a' > a_0, \\ \{x \in V : \phi(x) < a_1 \} \text{ is not Runge in } \mathbb{C}^2$$

then there exists a unique real number  $r = r(\phi) \in [a_0, a_1)$  such that  $V_{r(\phi)} := \{x \in V : \phi(x) < r(\phi)\}$  is Runge and  $\overline{V}_{r(\phi)} = \{x \in V : \phi(x) \le r(\phi)\}$  is not holomorphically convex. Note that  $V_{r(\phi)}$  must be connected since each of its components contains a (minimum) critical point,  $V_{r(\phi)}$  contains  $\{x \in V : \phi(x) < a_0\}$  which is connected and  $\{x \in V : \phi(x) < a_0\} \supset C(\phi)$ . We also proved that there exists a real analytic function  $\phi$  satisfying (\*). We fix such a  $\phi$ . Shrinking V we can assume that  $\overline{V}$  is compact and that  $\phi$  is defined on a neighborhood of  $\overline{V}$ .

Next we want to show that there exists  $\psi$ , a small perturbation of  $\phi$ , which satisfies (\*) and in addition it has the following geometric property: for every complex line l the set  $\mathcal{T}(\psi, l) := \{x \in \partial V_{r(\psi)} \cap l : l \text{ is tangent to } \partial V_{r(\psi)} \text{ at } x\}$  is finite.

Indeed: let U be an open and connected set such that  $C(\phi) \subset U \subset V_{r(\phi)}$  and let W be an open and relatively compact neighborhood of  $\partial V_{r(\phi)}$  and  $0 < \delta < \delta' < a_1 - r(\phi)$  two real numbers such that  $U \subset \{x \in V : \phi(x) < r(\phi) - \delta\}$  and  $\{x \in V : r(\phi) - \delta < \phi(x) < r(\phi) + \delta\} \subset W \subset \{x \in V : \phi(x) < r(\phi) + \delta'\}$ .

If  $\epsilon > 0$  is small enough then, for every  $\psi : V \to \mathbb{R}$ , a  $\mathcal{C}^{\infty}$  function, if the sup norms on  $\overline{V}$  of  $\psi - \phi$ ,  $\frac{\partial(\psi - \phi)}{\partial x_j}$ ,  $\frac{\partial^2(\psi - \phi)}{\partial x_j \partial x_k}$ , j, k = 1, ..., n (here we

denote  $z_i = x_{2i-1} + ix_{2i}$  are less than  $\epsilon$ , then  $\psi$  is strictly plurisubharmonic and satisfies (\*). Moreover  $C(\psi) \subset U$ ,  $r(\psi) \in [r(\phi) - \delta, r(\phi) + \delta]$  and  $\partial \{x \in V : \psi < s\} \subset W$  for every  $s \in [r(\phi) - \delta, r(\phi) + \delta]$ . We claim that there exists a real analytic  $\psi$  such that for every complex line l and for every  $s \in [r(\phi) - \delta, r(\phi) + \delta]$  the following set  $\mathcal{T}(\psi, l, s) := \{x \in \partial \{x \in V : \psi(x) < \delta\}\}$  $s \cap l : l$  is tangent to  $\partial \{x \in V : \psi(x) < s\}$  at  $x \in V$  is finite. Indeed, suppose that there exists  $x_0$  which is not isolated in some  $\mathcal{T}(\psi, l, s)$  (note that s is then  $\psi(x_0)$  and l is the complex tangent line at  $x_0$  to  $\{\psi=\psi(x_0)\}$ ). If we denote by  $u := \psi_{l}$  then  $x_0$  is not isolated in  $\{z \in l : u(z) = u(x_0), \ \nabla u(z) = 0\}$ . On the other hand u is real analytic and strictly subharmonic. It follows that around  $x_0$  at least one of the sets  $\{z \in l \cap V : \frac{\partial u}{\partial x}(z) = 0\}$  or  $\{z \in l \cap V : \frac{\partial u}{\partial x}(z) = 0\}$  $\frac{\partial u}{\partial y}(z) = 0$  is smooth and then the smooth one is contained in the other one. Hence there exists around  $x_0$  a smooth real analytic curve C such that  $u_{|C} = \text{constant} = u(x_0)$  and  $\nabla u_{|C} = 0$ . If  $\{f = 0\}$  is a local equation for C and a is any point on C it follows that in a neighborhood of a, u can be written as  $u = u(a) + f^2g$ . This shows that if

- (\*) There exists l and s such that  $\mathcal{T}(\psi, l, s)$  is not finite, then
- (\*\*) There exists a complex line L, a constant k, and a germ of smooth real analytic curve C in L such that in a neighborhood of each point of C  $\psi_{|L} = k + f^2 g$  where f is a local defining function for C.

Assume that (\*\*) holds.

Let a be any point on C. It follows that L is the complex tangent line at a to  $\{\psi = k\}$  and therefore a parametrization for L is

$$\lambda \to \left(\frac{\partial \psi}{\partial z_2}(a)\lambda, -\frac{\partial \psi}{\partial z_1}(a)\lambda\right) + a$$

We write  $\lambda = s + it$  and we consider the one complex variable function  $\psi_1$  given by  $\psi_1(\lambda) = \psi((\frac{\partial \psi}{\partial z_2}(a)\lambda, -\frac{\partial \psi}{\partial z_1}(a)\lambda + a)$ . Then  $\psi_1$  is strictly subharmonic around 0 hence at least one of  $\frac{\partial^2 \psi_1}{\partial s^2}(0), \frac{\partial^2 \psi_1}{\partial t^2}(0)$  is positive. Without loss of generality we assume that  $\frac{\partial^2 \psi_1}{\partial s^2}(0)$  is positive. Then, around 0, we have:  $\psi_1 = \psi_1(0) + \left((2\frac{\partial^2 \psi_1}{\partial s^2}(0))^{-1/2}\frac{\partial \psi_1}{\partial s}\right)^2 g(\lambda)$ , where g is a real analytic function with g(0) = 1. It follows that

(1) 
$$\det Hess(\psi_1)(0,0) = 0$$

and if we consider the linear change of coordinates  $\chi(s,t)=(\sigma,\tau)$  with  $\sigma=(2\frac{\partial^2\psi_1}{\partial s^2}(0))^{-1/2}(\frac{\partial^2\psi_1}{\partial s^2}(0)s+\frac{\partial^2\psi_1}{\partial s\partial t}(0)t),\ \tau=t,$  and we set  $\psi_2=\psi_1\circ\chi^{-1}$  we also have, at 0,

$$(2) \frac{\partial^3 \psi_2}{\partial \tau^3} (0,0) = 0$$

$$(3) \frac{2}{3} \frac{\partial^4 \psi_2}{\partial \tau^4} (0,0) = \left[ \frac{\partial^3 \psi_2}{\partial \sigma \partial \tau^2} (0,0) \right]^2$$

$$(4) \ \ \tfrac{4}{5!} \tfrac{\partial^5 \psi_2}{\partial \tau^5}(0,0) = [\tfrac{1}{6} \tfrac{\partial^4 \psi_2}{\partial \sigma \partial \tau^3}(0,0) - \tfrac{1}{8} \tfrac{\partial^3 \psi_2}{\partial \sigma \partial \tau^2}(0,0) \tfrac{\partial^3 \psi_2}{\partial \sigma^2 \partial \tau}(0,0)] \tfrac{\partial^3 \psi_2}{\partial \sigma \partial \tau^2}(0,0).$$

Note also that all these four relations can be expressed only in terms of  $\psi$ , without involving L, s, t,  $\sigma$  or  $\tau$ .

$$\left( \text{E.g. } \frac{\partial^2 \psi_1}{\partial s^2}(0,0) = \frac{\partial^2 \psi}{\partial z_1^2}(a) \left( \frac{\partial \psi}{\partial z_2}(a) \right)^2 + \frac{\partial^2 \psi}{\partial \overline{z}_1^2}(a) \left( \overline{\frac{\partial \psi}{\partial z_2}(a)} \right)^2 + 2 \frac{\partial^2 \psi}{\partial z_1 \partial \overline{z}_1}(a) \left| \frac{\partial \psi}{\partial z_1}(a) \right|^2 + \frac{\partial^2 \psi}{\partial z_2^2}(a) \left( \frac{\partial \psi}{\partial z_1}(a) \right)^2 + \frac{\partial^2 \psi}{\partial \overline{z}_2^2}(a) \left( \overline{\frac{\partial \psi}{\partial z_1}(a)} \right)^2 + 2 \frac{\partial^2 \psi}{\partial z_2 \partial \overline{z}_2}(a) \left| \frac{\partial \psi}{\partial z_1}(a) \right|^2 - 2 \frac{\partial^2 \psi}{\partial z_1 \partial z_2}(a) \frac{\partial \psi}{\partial z_2}(a) \frac{\partial \psi}{\partial z_1}(a) - 2 \frac{\partial^2 \psi}{\partial \overline{z}_1 \partial \overline{z}_2}(a) \overline{\frac{\partial \psi}{\partial z_1}(a)} - 2 \frac{\partial^2 \psi}{\partial \overline{z}_1 \partial \overline{z}_2}(a) \overline{\frac{\partial \psi}{\partial z_1}(a)} \overline{\frac{\partial \psi}{\partial z_1}(a)} - 2 \frac{\partial^2 \psi}{\partial \overline{z}_1 \partial \overline{z}_2}(a) \overline{\frac{\partial \psi}{\partial z_1}(a)} \overline{\frac{\partial \psi}{\partial z_1}(a)} - 2 \frac{\partial^2 \psi}{\partial \overline{z}_1 \partial \overline{z}_2}(a) \overline{\frac{\partial \psi}{\partial z_1}(a)} \overline{\frac{\partial \psi}{\partial z_1}(a)} - 2 \overline{\frac{\partial \psi}{\partial z_1}(a)} \overline{\frac$$

They are, in fact, four differential equations that must be satisfied by  $\psi$  at each point  $a \in C$ . For a generic real analytic function  $\psi$  the intersection of the four real analytic sets defined by this four equations is discrete ( $\psi$  is defined on  $\mathbb{C}^2 \equiv \mathbb{R}^4$ ) hence it cannot contain C (the germ of a real analytic curve). As a matter of fact, from  $\psi_{|L} = k + f^2 g$  one can come up with as many differential equations as one wants, but their are more and more complicated.

We fix now a  $\psi$  which satisfies (\*) and the geometrical property mentioned above.

Our next goal will be to show that, for every complex line l in  $\mathbb{C}^2$ ,  $l \cap \overline{V}_{r(\psi)}$  is polynomially convex (although  $\overline{V}_{r(\psi)}$  is not). Note that  $(l \cap \overline{V}_{r(\psi)}) \setminus \overline{l \cap V_{r(\psi)}}$  is a finite set (as a subset of  $T(\psi, l)$ ). Hence it suffices to show that  $\overline{l \cap V_{r(\psi)}}$  is polynomially convex. Let's assume that it is not. Note that  $l \cap V_{r(\psi)}$  is Runge in l (since  $V_{r(\psi)}$  is Runge in  $\mathbb{C}^2$ ) and that it has a smooth boundary except at a finite set of points (the set of points of non-smoothness is also a subset of  $T(\psi, l)$ ). As we assumed that  $\overline{l \cap V_{r(\psi)}}$  is not polynomially convex it follows

that there exists a rectifiable loop  $\gamma$  in l such that  $\gamma\setminus (l\cap V_{r(\psi)})$  contains only points where the boundary of  $l\cap V_{r(\psi)}$  in l is not smooth and therefore is finite and  $\widehat{\gamma}\cap (l\setminus (\overline{l\cap V_{r(\psi)}}))\neq\emptyset$  (in fact it has a nonempty interior). Using again the finiteness of  $\mathcal{T}(\psi,l)$  it follows that  $\widehat{\gamma}\cap (\mathbb{C}^2\setminus \overline{V}_{r(\psi)})\neq\emptyset$ . We claim that there exists a  $\mathcal{C}^\infty$  family of biholomorphisms  $\{f_\epsilon:\mathbb{C}^2\to\mathbb{C}^2\}_{\epsilon\in\mathbb{R}}$  such that  $f_0$  is the identity and for  $\epsilon>0$  small enough  $f_\epsilon(\gamma)\subset V_{r(\psi)}$ . Without loss of generality we can assume that  $l=\{z=(z_1,z_2)\in\mathbb{C}^2:z_2=0\}$ . We write  $\gamma\setminus (l\cap V_{r(\psi)})=:\{(p_1,0),\ldots,(p_s,0)\}$  and we denote by  $(0,q_1),\ldots (0,q_s)$  the unit inner normals to  $\partial V_{r(\psi)}$ . We choose  $h:\mathbb{C}\to\mathbb{C}$  a holomorphic function such that  $h(p_j)=q_j$  and we define  $f_\epsilon(z)=(z_1,z_2+\epsilon h(z_1))$ . It is obvious that  $f_\epsilon$  are biholomorphisms and since  $\frac{\mathrm{d}f_\epsilon}{\mathrm{d}\epsilon}(p_j,0)=(0,q_j)$  it follows that  $f_\epsilon$  have the sought properties. Because  $\widehat{\gamma}\cap (\mathbb{C}^2\setminus \overline{V}_{r(\psi)})\neq\emptyset$  and  $\{f_\epsilon\}$  is a continuous family we deduce that for  $\epsilon$  small enough  $f_\epsilon(\widehat{\gamma})\neq\emptyset$  and  $f_\epsilon(\widehat{\gamma})$  and  $f_\epsilon(\gamma)\subset V_{r(\psi)}\cap f_\epsilon(l)$ . It follows from here that  $V_{r(\psi)}\cap f_\epsilon(l)$  is not Runge in  $f_\epsilon(l)$  which is a contradiction since  $V_{r(\psi)}$  is Runge in  $\mathbb{C}^2$  and  $f_\epsilon(l)$  is a closed analytic submanifold in  $\mathbb{C}^2$ .

We are now ready to produce our example. For  $\epsilon > 0$  we set  $W_{\epsilon} := \{x \in V : \psi(x) < r(\psi) + \epsilon\}$ . It follows from the definition of  $r(\psi)$  that  $W_{\epsilon}$  is not Runge in  $\mathbb{C}^2$ . We wish to prove that there exists  $\epsilon > 0$  such that for every complex line l,  $W_{\epsilon} \cap l$  is Runge in l.

Suppose that this is not the case. Then for  $n \in \mathbb{N}$  large enough there exists a complex line  $l_n$  such that  $W_{\frac{1}{n}} \cap l_n$  is not Runge in  $l_n$ . Note that  $\{l_n\}$  is a sequence of lines that intersect a given compact subset of  $\mathbb{C}^2$ . It contains then a convergent subsequence. By passing to this subsequence we can assume that  $\{l_n\}$  converges to a line l.

We already proved that  $l \cap V_{r(\psi)}$  is holomorphically convex and this implies that there exists  $\Omega$  a Runge open subset of  $\mathbb{C}^2$  such that  $l \cap \overline{V}_{r(\psi)} \subset \Omega \subset V$ . As  $\cap W_{\frac{1}{n}} = \overline{V}_{r(\psi)}$  and  $l_n$  converges to l we deduce that there exists  $n_0 \in \mathbb{N}$  such that, for every  $n \geq n_0$ ,  $W_{\frac{1}{n}} \cap l_n \subset \Omega$ . Hence  $W_{\frac{1}{n}} \cap l_n = (W_{\frac{1}{n}} \cap \Omega) \cap l_n$ . On the other hand,  $\psi$  is a plurisubharmonic function defined on the whole  $\Omega$  which is Stein and therefore  $W_{\frac{1}{n}} \cap \Omega$ , which is a level set for  $\psi_{|\Omega}$ , is Runge in  $\Omega$ . Since  $\Omega$  is Runge in  $\mathbb{C}^2$  it follows that  $W_{\frac{1}{n}} \cap \Omega$  is also Runge in  $\mathbb{C}^2$  and from here we obtain that  $W_{\frac{1}{n}} \cap l_n$  is Runge in  $l_n$ . This contradicts our assumption.

In conclusion, we proved that for  $\epsilon > 0$  small enough  $W_{\epsilon}$  is bounded,

strictly pseudoconvex, is not Runge in  $\mathbb{C}^2$  and for every complex line l in  $\mathbb{C}^2$ ,  $W_{\epsilon} \cap l$  is Runge in l. In the same way as before  $W_{\epsilon}$  must be connected since each of its components contains a critical point of  $\psi$ .

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Cezar Joiţa Institute of Mathematics of the Romanian Academy P.O. Box 1-764, Bucharest 014700 ROMANIA

E-mail address: Cezar.Joita@imar.ro