

Deux problèmes variationnels liés aux opérateurs en forme divergence avec symbole à croissance rapide

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joint work with *Marian Bocea*

Transitions de phase et équations non locales
IMAR, Bucharest

April 27, 2018

Definition of rapidly growing operators in divergence form

- $\Phi : \mathbb{R} \rightarrow \mathbb{R}^+$ is called **N -function** if Φ is even, convex; $\Phi(t) = 0$ iff $t = 0$; $\lim_{t \rightarrow 0} t^{-1}\Phi(t) = 0$ and $\lim_{t \rightarrow \infty} t^{-1}\Phi(t) = \infty$;
- assume Φ is C^1 and let $\varphi := \Phi'$ and define

$$\varphi^- := \inf_{s>0} \frac{s\varphi(s)}{\Phi(s)} \quad \text{and} \quad \varphi^+ := \sup_{s>0} \frac{s\varphi(s)}{\Phi(s)};$$

If

$$1 < \varphi^- \quad \text{and} \quad \varphi^+ = \infty,$$

we call the operator

$$\operatorname{div} \left(\frac{\varphi(|\nabla u|)}{|\nabla u|} \nabla u \right),$$

a rapidly growing operator in divergence form.

Examples: For each $p \in (1, \infty)$ rapidly growing operators in divergence form can be built with the aid of the following N -functions

$$\Phi(t) = \exp(|t|^p) - 1;$$

$$\Phi(t) = \sinh(|t|^p) = \frac{\exp(|t|^p) - \exp(|t|^{-p})}{2};$$

$$\Phi(t) = \cosh(|t|^p) - 1 = \frac{\exp(|t|^p) + \exp(|t|^{-p})}{2} - 1.$$

For

$$\Phi(t) = \exp(|t|^p) - 1,$$

we have

$$\varphi(t) = p \exp(|t|^p) |t|^{p-2} t.$$

A solution u of the equation

$$\operatorname{div} \left(\frac{\varphi(|\nabla u|)}{|\nabla u|} \nabla u \right) = 0,$$

will be called an **exponentially harmonic function**.

Outline:

- I. Exponentially harmonic maps and related problems;
- II. Minimization problems for inhomogeneous Rayleigh quotients.

In the rest of the presentation let $\Omega \subset \mathbb{R}^D$ ($D \geq 1$)
be an open, bounded, convex domain with smooth
boundary, $\partial\Omega$.

I. Exponentially harmonic maps and related problems

Let $g \in C^1(\Omega) \cap C(\bar{\Omega})$ be given. Consider the problem

$$\begin{cases} -\Delta u - 2\Delta_{\infty} u = 0 & \text{in } \Omega \\ u = g & \text{on } \partial\Omega. \end{cases} \quad (1)$$

Theorem. (Lieberman, 1992)

Define

$$W_g^{1,1}(\Omega) := \{w \in W^{1,1}(\Omega) : w = g \text{ on } \partial\Omega\}.$$

If there exists $v \in W_g^{1,1}(\Omega)$ s.t.

$$\int_{\Omega} e^{|\nabla v|^2} dx \leq \int_{\Omega} e^{|\nabla w|^2} dx, \quad \forall w \in W_g^{1,1}(\Omega),$$

then v is a classical solution of problem (1).

Note that the problem (1) is equivalent to

$$\begin{cases} -\operatorname{div}(e^{|\nabla u|^2} \nabla u) = 0 & \text{in } \Omega \\ u = g & \text{on } \partial\Omega. \end{cases} \quad (2)$$

The integral from the above **Theorem**, i.e.,

$$u \longrightarrow \int_{\Omega} e^{|\nabla u|^2} dx,$$

plays the role of the **Euler-Lagrange functional** for problem (2).

Lieberman refers to **Duc & Eells** (1991) for alternative methods showing that a minimizer of the above integral is a weak solution of (2). Here we propose a different approach that is more natural from the point of view of the calculus of variations.

A suitable function space for analyzing problem (1) from a variational point of view is an Orlicz-Sobolev space, denoted by

$$W^{1,\Phi}(\Omega),$$

corresponding to the N -function

$$\Phi : \mathbb{R} \rightarrow \mathbb{R}, \quad \Phi(t) := e^{t^2} - 1,$$

whose derivative

$$\varphi(t) := 2te^{t^2},$$

is an odd, increasing homeomorphism from \mathbb{R} onto \mathbb{R} .

- $W^{1,\Phi}(\Omega)$ is not reflexive but it is a weakly* closed subset of the dual of a separable space;
- $W^{1,\Phi}(\Omega) \subset W^{1,q}(\Omega)$, for all $q \in (1, \infty)$.

The natural Euler-Lagrange functional corresponding to problem (2) is

$I : W^{1,\Phi}(\Omega) \rightarrow \mathbb{R}$ defined by

$$I(u) := \int_{\Omega} \Phi(|\nabla u(x)|) dx = \int_{\Omega} \left(e^{|\nabla u(x)|^2} - 1 \right) dx ,$$

or its equivalent form,

$$J(u) := \int_{\Omega} e^{|\nabla u(x)|^2} dx .$$

To account for the **boundary condition in (2)**, we need to consider the **restriction of I** to a proper subset of the Orlicz-Sobolev space $W^{1,\Phi}(\Omega)$, namely

$$X := W^{1,\Phi}(\Omega) \cap \left(\bigcap_{q>1} W_g^{1,q}(\Omega) \right),$$

where, for each $q \in (1, \infty)$,

$$W_g^{1,q}(\Omega) := \{u \in W^{1,q}(\Omega) \mid u = g \text{ on } \partial\Omega\},$$

is a **closed** and **convex** subset of the Sobolev space $W^{1,q}(\Omega)$.

- X is **NOT** a linear subspace of $W^{1,\Phi}(\Omega)$ (except when $g = 0$)
- X is a **convex** and **closed** subset of $W^{1,\Phi}(\Omega)$.
- I is **convex** and **weakly*** lower semicontinuous, but $I \notin C^1(W^{1,\Phi}(\Omega), \mathbb{R})$.

Our main result is the following theorem.

Theorem 1. *(Bocea & M, 2018) The functional I admits a unique minimizer in X , and this is the unique classical solution of the problem (1).*

Proof of Theorem 1 (existence of a minimizer)

For each integer $n \geq 2$, consider the family of problems

$$\begin{cases} -\sum_{k=1}^n \frac{1}{(k-1)!} \Delta_{2k} u = 0 & \text{in } \Omega \\ u = g & \text{on } \partial\Omega, \end{cases} \quad (3)$$

where $\Delta_{2k} u := \operatorname{div}(|\nabla u|^{2k-2} \nabla u)$ stands for the $2k$ -Laplace operator.

A weak solution of the problem (3) is a function $u \in W_g^{1,2n}(\Omega)$ such that

$$\sum_{k=1}^n \frac{1}{(k-1)!} \int_{\Omega} |\nabla u|^{2k-2} \nabla u \nabla \varphi \, dx = 0 \quad \forall \varphi \in W_0^{1,2n}(\Omega). \quad (4)$$

Lemma 1. *For each integer $n \geq 2$, the problem (3) admits a unique weak solution.*

Lemma 2. *For each integer $n \geq 2$, let $u_n \in W_g^{1,2n}(\Omega)$ be a weak solution of the problem (3). Then there exists a subsequence of $\{u_n\}$ that converges uniformly in Ω to some function $u_\infty \in C(\overline{\Omega})$.*

A Γ -convergence result

Lemma 3. Define $J_n : L^1(\Omega) \rightarrow \overline{\mathbb{R}}$ ($n \geq 2$) and $J_\infty : L^1(\Omega) \rightarrow \overline{\mathbb{R}}$ by

$$J_n(u) := \begin{cases} \sum_{k=1}^n \frac{1}{k!} \int_{\Omega} |\nabla u|^{2k} dx & \text{if } u \in W_g^{1,2n}(\Omega) \\ +\infty & \text{if } u \in L^1(\Omega) \setminus W_g^{1,2n}(\Omega), \end{cases}$$

and

$$J_\infty(u) := \begin{cases} \int_{\Omega} \left(e^{|\nabla u|^2} - 1 \right) dx & \text{if } u \in X \\ +\infty & \text{if } u \in L^1(\Omega) \setminus X, \end{cases}$$

respectively.

$$\Gamma(L^1(\Omega)) - \lim_{n \rightarrow \infty} J_n = J_\infty.$$

Proposition 1. Let Y be a topological space satisfying the first axiom of countability, and assume that the sequence $\{F_n\}$ of functionals $F_n : Y \rightarrow \overline{\mathbb{R}}$ Γ -converge to $F : Y \rightarrow \overline{\mathbb{R}}$. Let z_n be a minimizer for F_n . If $z_n \rightarrow z$ in Y , then z is a minimizer of F , and $F(z) = \liminf_{n \rightarrow \infty} F_n(z_n)$.

Taking into account Lemmas 1, 3, and 2, we can now apply Proposition 1 with $Y = L^1(\Omega)$, $F_n = J_n$, $F = J_\infty$, $z_n = u_n$ to deduce the existence of a minimizer for J_∞ and consequently a minimizer for I on X .

Connections with infinity harmonic and harmonic functions

For each real parameter $\varepsilon > 0$, consider the problem

$$\begin{cases} -\varepsilon\Delta u - 2\Delta_\infty u = 0 & \text{in } \Omega \\ u = g & \text{on } \partial\Omega. \end{cases} \quad (5)$$

This problem is equivalent to

$$\begin{cases} -\operatorname{div} \left(e^{\varepsilon^{-1}|\nabla u|^2} \nabla u \right) = 0 & \text{in } \Omega \\ u = g & \text{on } \partial\Omega, \end{cases} \quad (6)$$

which can be analyzed using [similar arguments](#) to those used for problem (2). The Euler-Lagrange functional for problem (6) is $J_\varepsilon : W^{1,\Phi}(\Omega) \rightarrow \mathbb{R}$ given by

$$J_\varepsilon(u) := \int_\Omega e^{\varepsilon^{-1}|\nabla u|^2} dx.$$

Arguing as for problem (2), it can be shown that $u_\varepsilon \in X$ is the unique minimizer of J_ε in X .

Thus, for each $\varepsilon > 0$ problem (5) has a unique classical solution $u_\varepsilon \in X$.

The limit of u_ε as $\varepsilon \rightarrow 0^+$

Let u be the (unique; by **Jensen**, 1993) viscosity solution of the problem

$$\begin{cases} -\Delta_\infty u = 0 & \text{in } \Omega \\ u = g & \text{on } \partial\Omega. \end{cases} \quad (7)$$

Theorem (Evans & Yu, 2007) *For every integer $m > D$, the sequence*

$\{u_\varepsilon\}$ is bounded in $W^{1,2m}(\Omega)$. Moreover, u_ε converges uniformly to u in

$\overline{\Omega}$ as $\varepsilon \rightarrow 0^+$.

The limit of u_ε as $\varepsilon \rightarrow \infty$

Let v be the **unique solution** of the problem

$$\begin{cases} -\Delta v = 0 & \text{in } \Omega \\ v = g & \text{on } \partial\Omega. \end{cases} \quad (8)$$

Theorem 2. (Bocea & M, 2018) *The sequence $\{u_\varepsilon\}$ converges to v in*

$W^{1,4}(\Omega)$ as $\varepsilon \rightarrow \infty$. Consequently, if $D \leq 3$ then u_ε converges to v

uniformly in $\bar{\Omega}$ as $\varepsilon \rightarrow \infty$.

II. Minimization problems for inhomogeneous Rayleigh quotients

Let $p \in (1, \infty)$.

Our goal is to analyze the minimization problem

$$\inf_{u \in X_0 \setminus \{0\}} \frac{\int_{\Omega} (\exp(|\nabla u|^p) - 1) dx}{\int_{\Omega} (\exp(|u|^p) - 1) dx},$$

where $X_0 = W^{1,\infty}(\Omega) \cap (\cap_{q>1} W_0^{1,q}(\Omega))$ and to discuss some related problems.

Motivation

Given an N -function $\Phi : \mathbb{R} \rightarrow \mathbb{R}^+$ (i.e., Φ is even, convex; $\Phi(t) = 0$ iff $t = 0$; $\lim_{t \rightarrow 0} t^{-1}\Phi(t) = 0$ and $\lim_{t \rightarrow \infty} t^{-1}\Phi(t) = \infty$), consider the minimization problem

$$\lambda_\Phi := \inf_{u \in W_0^{1,\Phi}(\Omega) \setminus \{0\}} \frac{\int_\Omega \Phi(|\nabla u|) dx}{\int_\Omega \Phi(|u|) dx}, \quad (9)$$

where $W_0^{1,\Phi}(\Omega)$ is a function space (an Orlicz-Sobolev type space) built with the aid of the N -function Φ .

A particular case

- If $\Phi(t) = \Phi_p(t) := |t|^p$ with $p \in (1, \infty)$, (9) has been investigated in connection with the *eigenvalue problem for the p -Laplacian*

$$\begin{cases} -\operatorname{div}(|\nabla u|^{p-2}\nabla u) = \lambda|u|^{p-2}u & \text{for } x \in \Omega \\ u = 0 & \text{for } x \in \partial\Omega. \end{cases} \quad (10)$$

In this case, λ_{Φ_p} is denoted by $\lambda_1(p)$ (or $\lambda_1(p; \Omega)$).

More precisely, in this case

$$\lambda_1(p) = \inf_{u \in W_0^{1,p}(\Omega) \setminus \{0\}} \frac{\int_{\Omega} |\nabla u|^p dx}{\int_{\Omega} |u|^p dx}.$$

Properties of $\lambda_1(p; \Omega)$

Fix $p \in (1, \infty)$.

- If $\Omega_1 \subset \Omega_2$ then $\lambda_1(p; \Omega_1) \geq \lambda_1(p; \Omega_2)$.
- $\lambda_1(p; B_R) = R^{-p} \lambda_1(p; B_1)$, for each $R > 0$, $p \in (1, \infty)$ and B_R ball of radius R .

Fix $\Omega \subset \mathbb{R}^D$.

- The map $\lambda_1(\cdot; \Omega) : (1, \infty) \rightarrow (0, \infty)$ is continuous (**Lindqvist** 1993, **Huang** 1997).

- If

$$\Lambda_\infty(\Omega) := \inf_{\varphi \in X_0 \setminus \{0\}} \frac{\|\nabla \varphi\|_{L^\infty(\Omega)}}{\|\varphi\|_{L^\infty(\Omega)}} \quad (11)$$

it is known that $\Lambda_\infty(\Omega) = \|\delta\|_{L^\infty(\Omega)}^{-1}$ (**Juutinen, Lindqvist, & Manfredi, 1999; Fukagai, Ito & Narukawa 1999**) and

$$\lim_{p \rightarrow \infty} \sqrt[p]{\lambda_1(p; \Omega)} = \Lambda_\infty(\Omega) = \|\delta\|_{L^\infty(\Omega)}^{-1},$$

here $\delta : \Omega \rightarrow [0, \infty)$ stands for the distance function to $\partial\Omega$, namely

$$\delta(x) := \text{dist}(x, \partial\Omega) = \inf_{y \in \partial\Omega} |x - y|, \quad \forall x \in \Omega.$$

It is also well-known that $\Lambda_\infty(\Omega) = R_\Omega^{-1}$, where R_Ω stands for the radius of the largest ball contained in Ω .

- The map $\lambda_1(\cdot; \Omega) : (1, \infty) \rightarrow (0, \infty)$ is **not monotone** for general domains Ω (**Bobkov & Tanaka, 2015**).

Nevertheless, recall if $\partial\Omega$ is sufficiently smooth, then (**Lindqvist 1993**) function

$$(1, \infty) \ni p \longrightarrow p \sqrt[p]{\lambda_1(p; \Omega)},$$

is increasing, i.e.

$$t \sqrt[t]{\lambda_1(t; \Omega)} \leq s \sqrt[s]{\lambda_1(s; \Omega)}, \quad \forall 1 < t < s < \infty.$$

- The following estimate holds true (**Kajikia** 2015)

$$\frac{p-1}{R_\Omega^p} \left(\frac{\pi/p}{\sin(\pi/p)} \right)^p \leq \lambda_1(p; \Omega) \leq \lambda_1(p; B_{R_\Omega}).$$

This result is **sharp** in the sense that we know that the left hand side represents the infimum of $\lambda_1(p; \Omega)$ over all convex, bounded domains that have the radius of the largest inscribed ball equal to R_Ω .

More precisely, if we define, for $T > 0$, $\Omega(T) := (-R_\Omega, R_\Omega) \times B_T^{D-1}(0)$, where $B_T^{D-1}(0)$ stands for the ball in \mathbb{R}^{D-1} centered at the origin and with radius T , then

$$\lim_{T \rightarrow \infty} \lambda_1(p; \Omega(T)) = \frac{p-1}{R_\Omega^p} \left(\frac{\pi/p}{\sin(\pi/p)} \right)^p.$$

Back to the general case

- Denote $\varphi(t) := \Phi'(t)$. If

$$1 \leq \varphi^- := \inf_{s>0} \frac{s\varphi(s)}{\Phi(s)} \leq \frac{t\varphi(t)}{\Phi(t)} \leq \sup_{s>0} \frac{s\varphi(s)}{\Phi(s)} =: \varphi^+ < \infty \quad \forall t > 0,$$

then it can be showed that $\lambda_\Phi > 0$ (**Gossez**, 1974; **Bocea & M**, 2012).

- If $1 < \varphi^- \leq \varphi^+ \leq \infty$, it was established the fact that for each $r > 0$ the minimization problem

$$\Lambda_r := \inf \left\{ \int_{\Omega} \Phi(|\nabla u|) dx : u \in W_0^{1,\Phi}(\Omega), \int_{\Omega} \Phi(|u|) dx = r \right\},$$

has a solution u_r (**Mustonen & Tienari**, 1999). Here, $W_0^{1,\Phi}(\Omega)$ stands for the corresponding Orlicz-Sobolev space associated to the N -function Φ . Moreover, u_r is a weak solution for the corresponding Euler-Lagrange equation, i.e.

$$\begin{cases} -\operatorname{div} \left(\frac{\varphi(|\nabla u|)}{|\nabla u|} \nabla u \right) = \lambda_r \frac{\varphi(|u|)}{|u|} u & \text{for } x \in \Omega \\ u = 0 & \text{for } x \in \partial\Omega, \end{cases}$$

for some $\lambda_r > 0$. Note that the case $\varphi^+ = +\infty$ is allowed.

When $\varphi^+ = +\infty$, **Garcia-Huidobro, Le, Manasevich, & Schmitt** (1999) observed that we can have $\inf_{r>0} \Lambda_r \geq 0$, and thus $\lambda_\Phi = 0$ may, in fact, occur.

Back to our problem

Consider the minimization problem (9) when

$$\Phi(t) = \exp(|t|^p) - 1,$$

with $p \in (1, \infty)$, and when $W_0^{1,\Phi}(\Omega)$ is replaced by

$$X_0 = W^{1,\infty}(\Omega) \cap \left(\bigcap_{q>1} W_0^{1,q}(\Omega) \right),$$

i.e.,

$$\Lambda_1(p) := \inf_{u \in X_0 \setminus \{0\}} \frac{\int_{\Omega} (\exp(|\nabla u|^p) - 1) \, dx}{\int_{\Omega} (\exp(|u|^p) - 1) \, dx}. \quad (12)$$

The **distance function** to $\partial\Omega$, namely $\delta : \Omega \rightarrow [0, \infty)$ defined by $\delta(x) := \text{dist}(x, \partial\Omega) = \inf_{y \in \partial\Omega} |x - y|$, plays a **key role** in establishing the **positivity** of $\Lambda_1(p)$.

Our results

First, we note that the following Hardy-type inequality related to the study of (12) can be established.

Theorem 3. (Bocea & M, 2018) *For each $p \in (1, \infty)$ we have*

$$\inf_{u \in C_0^\infty(\Omega) \setminus \{0\}} \frac{\int_{\Omega} (\exp(|\nabla u|^p) - 1) dx}{\int_{\Omega} \left(\exp\left(\left|\frac{u}{\delta}\right|^p\right) - 1 \right) dx} = \left(\frac{p-1}{p}\right)^p. \quad (13)$$

Remark.

By Theorem 3 we get that if $\|\delta\|_{L^\infty(\Omega)} \leq 1$ then

$$\inf_{u \in C_0^\infty(\Omega) \setminus \{0\}} \frac{\int_{\Omega} (\exp(|\nabla u|^p) - 1) dx}{\int_{\Omega} (\exp(|u|^p) - 1) dx} > 0.$$

Indeed, if $\|\delta\|_{L^\infty(\Omega)} \leq 1$ then

$$\exp\left(\left|\frac{v(x)}{\delta(x)}\right|^p\right) - 1 \leq \exp(|v(x)|^p) - 1, \quad \text{a.e. } x \in \Omega \quad \forall v \in C_0^\infty(\Omega), \quad \forall p > 1.$$

Thus, for each $v \in C_0^\infty(\Omega) \setminus \{0\}$ we have

$$\left(\frac{p-1}{p}\right)^p \leq \frac{\int_{\Omega} (\exp(|\nabla v|^p) - 1) dx}{\int_{\Omega} (\exp(|\delta|^{-p}|v|^p) - 1) dx} \leq \frac{\int_{\Omega} (\exp(|\nabla v|^p) - 1) dx}{\int_{\Omega} (\exp(|v|^p) - 1) dx}.$$

Next, we point out the main result on problem (12).

Theorem 4. (Bocea & M, 2018)

- if $\|\delta\|_{L^\infty(\Omega)} > 1$ then $\Lambda_1(p) = 0$;
- if $\|\delta\|_{L^\infty(\Omega)} \in (0, 1]$ then $\Lambda_1(p) > 0$;
- if $\|\delta\|_{L^\infty(\Omega)} \in (0, 1]$ then $\inf\{\lambda_1(kp) : k \in \mathbb{N}^*\} \leq \Lambda_1(p) \leq \lambda_1(p)$, for all $p \in (1, \infty)$;
- if $\|\delta\|_{L^\infty(\Omega)} \in (0, 1)$ then $\Lambda_1(p) = \lambda_1(p)$ for all $p > 1$ sufficiently large.

The proof of the case where $\|\delta\|_{L^\infty(\Omega)} > 1$

Let $\epsilon_0 > 0$ and $\omega \subset \Omega$ with $|\omega| > 0$ s.t.

$$\delta(x) \geq 1 + \epsilon_0, \quad \forall x \in \omega.$$

Since $\delta \in X_0 \setminus \{0\}$,

$$\Lambda_1(p) \leq \frac{\int_{\Omega} (\exp(|\nabla(n\delta)|^p) - 1) dx}{\int_{\Omega} (\exp((n\delta)^p) - 1) dx} \quad \forall n \geq 1. \quad (14)$$

Taking into account that $|\nabla\delta(x)| = 1$ for a.e. $x \in \Omega$, we have

$$\begin{aligned} \frac{\int_{\Omega} (\exp(|\nabla(n\delta)|^p) - 1)}{\int_{\Omega} (\exp((n\delta)^p) - 1)} &= \frac{|\Omega|(\exp(n^p) - 1)}{\int_{\Omega} (\exp(n^p\delta(x)^p) - 1)} \leq \frac{|\Omega|(\exp(n^p) - 1)}{\int_{\omega} (\exp(n^p\delta(x)^p) - 1)} \\ &\leq \frac{|\Omega|(\exp(n^p) - 1)}{|\omega|(\exp(n^p(1 + \epsilon_0)^p) - 1)}, \end{aligned}$$

for every integer $n \geq 1$. The fact that $\Lambda_1(p) = 0$ now follows by letting $n \rightarrow \infty$ in (14).

We identify some cases where $\Lambda_1(p) = \lambda_1(p)$ for all $p \in (1, \infty)$.

The simplest such situation occurs in the **one-dimensional case**, when $\lambda_1(p)$ can be explicitly computed for every $p \in (1, \infty)$ (see, e.g. Lindqvist 1993) and thus, we can show that the function $(1, \infty) \ni p \rightarrow \lambda_1(p) \in (0, \infty)$ **is increasing** provided that $\|\delta\|_{L^\infty(\Omega)} \in (0, 1]$.

More precisely, the following result holds true.

Theorem 5. (Bocea & M, 2018)

- If $\Omega = (a, b)$ and $\|\delta\|_{L^\infty(\Omega)} \in (0, 1]$ then

$$\Lambda_1(p) = \lambda_1(p), \quad \forall p \in (1, \infty).$$

- In the D -dimensional case, $D \geq 2$, if $\|\delta\|_{L^\infty(\Omega)} \in (0, 1]$ and $\Omega := (-\|\delta\|_{L^\infty(\Omega)}, \|\delta\|_{L^\infty(\Omega)}) \times B_T^{D-1}(0)$, where $B_T^{D-1}(0)$ stands for the ball centered at the origin of radius T in \mathbb{R}^{D-1} then, for sufficiently large $T > 0$, we have

$$\Lambda_1(p) = \lambda_1(p), \quad \forall p \in (1, \infty).$$

Unfortunately, in dimensions two or higher, the **monotonicity** of the map $(1, \infty) \ni p \rightarrow \lambda_1(p) \in (0, \infty)$ when $\|\delta\|_{L^\infty(\Omega)} \in (0, 1]$ **is not known in general**. Nevertheless, using as our main argument the monotonicity property

$$t\sqrt[t]{\lambda_1(t; \Omega)} \leq s\sqrt[s]{\lambda_1(s; \Omega)}, \quad \forall 1 < t < s < \infty.$$

it can be shown that the above property remains valid in higher dimensions provided that the **volume of the domain where we investigate the problem is sufficiently small**.

Theorem 6. (Bocea & M, 2018)

- Assume that $D \geq 2$ and $\Omega \subset \mathbb{R}^D$ is an *open bounded domain* that satisfies $|\Omega| < v_D \exp(-D)$, where v_D denotes the volume of the unit ball in \mathbb{R}^D . Then

$$\Lambda_1(p) = \lambda_1(p), \quad \forall p \in (1, \infty).$$

We would like to point out that a well-known property of the principal frequency of the p -Laplacian **fails** to hold for Λ_1 .

Recall that,

$$\lambda_1(p; B_R) = R^{-p} \lambda_1(p; B_1), \quad \forall p \in (1, \infty), \text{ and } R > 0.$$

It follows that

$$\lim_{R \searrow 1} \lambda_1(p; B_R) = \lambda_1(p; B_1).$$

It is clear that this property fails if we replace λ_1 by Λ_1 , since in this case we have

$$\Lambda_1(p; B_R) = 0, \quad \forall p \in (1, \infty), \quad R > 1,$$

while

$$\Lambda_1(p; B_1) > 0, \quad \forall p \in (1, \infty).$$

Thank you for your attention!