

# Well-posedness of semilinear dissipative SPDEs with singular drift and semimartingale noise

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# The problem

Consider the SPDE

$$du + Au dt + \beta(u) dt = B(u) dZ, \quad u(0) = u_0,$$

with

- ▶  $A$  linear maximal monotone on  $H := L^2(D)$ ,  $D \subset \mathbb{R}^n$  smooth bounded domain;
- ▶  $\beta : \mathbb{R} \rightarrow \mathbb{R}$  increasing;
- ▶  $Z$  semimartingale with values in a (separable) Hilbert space  $K$ ;
- ▶  $B : \Omega \times \mathbb{R}_+ \times H \rightarrow \mathcal{L}(K, H)$  Lipschitz continuous.

– Questions –

- (a) Notion of solution
- (b) Existence of solutions
- (c) Uniqueness (conditional vs. unconditional)
- (d) Continuity of the map  $u_0 \mapsto u$
- (e) Regularity properties

## Motivation: random vs. non-random evolution equations

Let  $E$  be any Banach space,  $A$  nonlinear  $m$ -accretive on  $E$ ,  $\varphi \in L_1(0, T; E)$ .

**Theorem.** (Crandall-Liggett) The Cauchy problem

$$\frac{du}{dt} + Au \ni \varphi, \quad u(0) = u_0$$

is well-posed in the CL-mild sense.

- ▶ If  $E$  is Hilbert space, CL-mild solution is SOLA. (Bénilan-Brézis)
- ▶ If  $A = A_0 + f$ ,  $A_0$  linear  $m$ -accretive and  $f$  m.m. graph in  $\mathbb{R} \times \mathbb{R}$ , the problem is reduced to summing  $m$ -accretive operators.
- ✗ All proofs break down if  $\varphi$  is not a function.
- ↪ No well-posedness theory can be deduced for

$$du + Au dt = B dW, \quad u(0) = u_0.$$

- ✓ A stochastic well-posedness theory is available in some cases, e.g.
  - $A : V \rightarrow V'$ ,  $V \hookrightarrow H \hookrightarrow V'$  (Pardoux, Krylov-Rozovskiĭ, Gyöngy)
  - special settings, e.g.  $A = -\Delta\psi$ ,  $E = H^{-1}$  (Barbu-Da Prato-Röckner)

## Preliminaries: stochastic integration

**Definition.** A positive increasing adapted process  $C$  is a **control process** for  $Z$  if

$$(D) \quad \mathbb{E}(Y \cdot Z)_{T-}^{*2} \leq \mathbb{E}C_{T-}(\|Y\|^2 \cdot C)_{T-}$$

for every elementary  $\mathcal{L}(K, G)$ -valued  $Y$ , separable  $G$ , stopping time  $T$ .

**Theorem.**  $Z$  adapted càdlàg  $K$ -valued process is a semimartingale if and only if it admits a control process.

**Definition.** A strongly predictable  $\mathcal{L}(K, G)$ -valued process  $Y$  is integrable with respect to  $Z$  if there exists a control process  $C$  for  $Z$  such that the process

$$\lambda^C(Y) := C(\|Y\|^2 \cdot C)$$

is finite.

The construction of  $Y \cdot Z$  implies that the pre-stopped Doob inequality (D) remains true for every control process  $C$  and every  $Y$  with  $\lambda^C(Y)$  finite.

# Assumptions

- ▶  $A$  is variational:  $A \in \mathcal{L}(V, V')$  isomorphism,  $V$  Hilbert space densely, continuously, and compactly embedded in  $H$ , hence

$$\langle Av, v \rangle \geq c \|v\|_V^2;$$

- ▶  $A \cap (V \times H)$  admits  $m$ -accretive extension  $A_1$  to  $L^1(D)$ ;

- ▶  $A_1$  has sub-Markovian resolvent  $(I + \lambda A_1)^{-1}$ ;

- ▶  $(I + \lambda A_1)^{-m} \in \mathcal{L}(L^1(D), L^\infty(D))$  for some  $m \in \mathbb{N}$ .

- ▶  $\beta$  is an odd maximal monotone graph in  $\mathbb{R} \times \mathbb{R}$ ,  $D(\beta) = \mathbb{R}$ ,  $0 \in \beta(0)$

↪  $\exists$  l.s.c. convex even positive  $j$  such that  $\beta = \partial j$ ,  $j(0) = 0$ ,

$$\lim_{x \rightarrow \infty} \frac{j^*(x)}{|x|} = \infty.$$

- ▶  $B : \Omega \times \mathbb{R}_+ \times H \rightarrow \mathcal{L}(K, H)$  is such that  $B(\cdot, \cdot, u)$  is strongly predictable for every  $u \in H$ , and  $\forall C \in \mathcal{C}(Z)$  there exists  $L \in \mathcal{A}_+^\uparrow$  r.c. such that

$$\begin{aligned} \|B(u_-) - B(v_-)\|_{\mathcal{L}(K, H)}^2 \cdot C &\leq (u - v)_-^{*2} \cdot L, \\ \|B(u_-)\|_{\mathcal{L}(K, H)}^2 \cdot C &\leq (1 + u_-^{*2}) \cdot L \end{aligned}$$

for every adapted càdlàg processes  $u, v$ .

# Strong solutions

Let  $T_0 \in \mathbb{R}_+$  be a fixed final time.

**Definition.** Let  $T \leq T_0$  be a stopping time. A strong solution on  $\llbracket 0, T \rrbracket$  is a pair  $(u, \xi)$ , with

- ▶  $u$  adapted càdlàg  $H$ -valued,
- ▶  $\xi$  adapted  $L^1(D)$ -valued,

such that

- $\mathbb{1}_{\llbracket 0, T \rrbracket} u \in L^1(0, T_0; V)$ ,  $\mathbb{1}_{\llbracket 0, T \rrbracket} \xi \in L^1(\llbracket 0, T_0 \rrbracket \times D)$ ,  $\xi \in \beta(u)$  a.e. in  $\llbracket 0, T \rrbracket \times D$ ;
- $\mathbb{1}_{\llbracket 0, T \rrbracket} B(u_-)$  is integrable with respect to  $Z$ ;
- one has, as an identity in  $V' \cap L^1(D)$ ,

$$u^T + \int_0^{\wedge T} Au(s) ds + \int_0^{\wedge T} \xi(s) ds = u_0 + (\mathbb{1}_{\llbracket 0, T \rrbracket} B(u_-)) \cdot Z.$$

# Well-posedness

**Theorem.** Let  $u_0 \in L^0(\Omega, \mathcal{F}_0; H)$  and  $T_0 \in \mathbb{R}_+$ . Then

- (a) there exists a strong solution  $(u, \xi)$  on  $[0, T_0]$ ;
- (b) the solution is the only one such that

$$u_{T_0}^* + \|u\|_{L^2(0, T_0; V)} + \|u\xi\|_{L^1([0, T_0] \times D)} < \infty \quad \text{a.s.}$$

- (c)  $u$  and  $\xi$  are optional;
- (d) The solution map

$$\begin{aligned} L^0(\Omega; H) &\longrightarrow L^0(\Omega; D([0, T_0]; H) \cap L^2(0, T_0; V)) \\ u_0 &\longmapsto u \end{aligned}$$

is continuous.

## Remarks.

- (i) Unconditional well-posedness is open.
- (ii) More “precise” results if  $Z$  is a Wiener process.

# Main steps of the proof

1. Consider the equation

$$du_\lambda + A_\lambda u_\lambda dt + \beta_\lambda(u_\lambda) dt = G dZ, \quad u_\lambda(0) = u_0,$$

with

- ▶  $A_\lambda, \beta_\lambda$  Yosida approximations;
  - ▶  $G$  independent of  $u_\lambda$  and taking values in  $V_0 \hookrightarrow V \cap L^\infty(D)$ ;
  - ▶  $u_0 \in L^2(\Omega, \mathcal{F}_0; H)$ .
2. A priori estimates on  $u_\lambda$  and  $\beta_\lambda(u_\lambda)$ , both pathwise and in expectation.
- ↪ Compactness and passage to the limit in the equation solving

$$du + Au dt + \beta(u) dt = G dZ, \quad u(0) = u_0.$$

3. Removal of all restrictions on the data by further limiting procedures and localization.
4. General case  $G = B(u_-)$  by fixed point, construction of a local solution, and extension thereof.



## Existence for an auxiliary problem

We first consider the simpler problem

$$(G) \quad du + Au \, dt + \beta(u) \, dt = G \, dZ, \quad u(0) = u_0,$$

with  $G : \Omega \times [0, T_0] \rightarrow \mathcal{L}(K, V_0)$ ,  $V_0$  separable Hilbert space continuously embedded in  $V$  and  $L^\infty(D)$ ,  $\mathbb{E}\lambda_{T_0-}^C(G) < \infty$ ,  $\mathbb{E}\|u_0\|^2 < \infty$ .

**Proposition.** There exists a unique strong solution  $u$  to (G).

Let

$$A_\lambda := \frac{1}{\lambda}(I - (I + \lambda A)^{-1}), \quad \beta_\lambda := \frac{1}{\lambda}(I - (I + \lambda \beta)^{-1}), \quad \lambda > 0$$

be the Yosida regularizations of  $A$  and  $\beta$ , and consider

$$du_\lambda + A_\lambda u_\lambda \, dt + \beta_\lambda(u_\lambda) \, dt = G \, dZ, \quad u_\lambda(0) = u_0.$$

Since  $A_\lambda$  and  $\beta_\lambda$  are Lipschitz-continuous, a unique classical solution

$$u_\lambda \in \mathbb{S}^2(0, T_0)$$

exists.

## A priori estimates

By the assumptions on  $G$  it follows that  $G \cdot Z \in L^\infty(0, T; V_0)$ . The regularized equation can be written as

$$(u_\lambda - G \cdot W)' + A_\lambda u_\lambda + \beta_\lambda(u_\lambda) = 0 \quad \text{in } V'.$$

The integration-by-parts formula yields

$$\begin{aligned} \frac{1}{2} \|u_\lambda - G \cdot Z\|^2 + \int_0^\cdot \langle A_\lambda u_\lambda, u_\lambda - G \cdot Z \rangle \\ + \int_0^\cdot \int_D \beta_\lambda(u_\lambda)(u_\lambda - G \cdot Z) = \frac{1}{2} \|u_0\|^2. \end{aligned}$$

**Lemma.** For every  $\omega$  in a set of probability one there exists  $N = N(\omega)$  such that

$$\|u_\lambda(\omega)\|_{L^\infty(0, T_0; H)} < N(\omega),$$

$$\|J_\lambda u_\lambda(\omega)\|_{L^2(0, T_0; V)} < N(\omega),$$

$$\|\beta_\lambda(u_\lambda(\omega))u_\lambda(\omega)\|_{L^1([0, T_0] \times D)} < N(\omega).$$

## Compactness properties of $u_\lambda$ and $\beta_\lambda(u_\lambda)$

Recall that  $xy \leq j(x) + j^*(y)$ , with equality if and only if  $y \in \beta(x)$ . Since

$$j(J_\lambda u_\lambda) + j^*(\beta_\lambda(u_\lambda)) = \beta_\lambda(u_\lambda) J_\lambda u_\lambda \leq \beta_\lambda(u_\lambda) u_\lambda, \quad J_\lambda := (I + \lambda\beta)^{-1},$$

it follows by the symmetry of  $j$  that

$$\|j^*(|\beta_\lambda(u_\lambda)(\omega)|)\|_{L^1([0, T_0] \times D)} < N(\omega).$$

The hypothesis  $D(\beta) = \mathbb{R}$  implies  $\lim_{|r| \rightarrow \infty} \frac{j^*(r)}{|r|} = +\infty$ , hence, thanks to the criterion by de la Vallée-Poussin,  $(\beta_\lambda(u_\lambda))$  is uniformly integrable. The Dunford-Pettis theorem then yields the

**Lemma.**  $(\beta_\lambda(u_\lambda)(\omega))$  is relatively weakly compact in  $L^1([0, T_0] \times D)$ .

One has  $y'_\lambda + A_\lambda u_\lambda + \beta_\lambda(u_\lambda) = 0$ ,  $y_\lambda := u_\lambda - G \cdot Z \rightsquigarrow y'_\lambda$  is bounded in  $L^1(0, T_0; V'_0)$ . Since  $y_\lambda$  is bounded in  $L^2(0, T_0; V)$ , Simon's compactness criterion implies the

**Lemma.**  $(u_\lambda(\omega))$  is relatively compact in  $L^2(0, T_0; H)$ .

## Passage to the limit

Keep  $\omega \in \Omega$  fixed. By the pathwise estimates, we have (extracting subsequences)

$$\begin{aligned}u_\lambda &\longrightarrow u \quad \text{strongly in } L^2(0, T_0; H), \\u_\lambda &\longrightarrow u \quad \text{weakly}^* \text{ in } L^\infty(0, T_0; H), \\J_\lambda u_\lambda &\longrightarrow u \quad \text{weakly in } L^2(0, T_0; V), \\ \beta_\lambda(u_\lambda) &\longrightarrow \xi \quad \text{weakly in } L^1([0, T_0] \times D).\end{aligned}$$

This is enough to pass to the limit in the approximated equation. Moreover, by the strong-weak closure of  $\beta$  we deduce

$$\xi \in \beta(u) \quad \text{a.e. in } (0, T) \times D$$

and, by the lower semicontinuity of convex integrals,

$$\xi u = j(u) + j^*(\xi) \in L^1((0, T) \times D)$$

## Measurability of the processes $u$ and $\xi$

The construction of  $u$  and  $\xi$  does **not** imply their measurability in  $\omega$ , as the subsequences depend on  $\omega$ .

However, energy estimates and a uniqueness argument imply that there exists a sequence  $(\lambda_n)$  independent of  $\omega$  along which the previous convergences hold.

Using the Mazur lemma and lower semicontinuity of the norms, this implies the

**Proposition.**  $u$  and  $\xi$  are measurable adapted processes (in fact optional), and

$$u \in L^2(\Omega; L^\infty(0, T_0; H)) \cap L^2(\Omega \times [0, T_0]; V),$$

$$\xi \in L^1(\Omega \times [0, T_0] \times D),$$

$$\xi \in \beta(u) \quad \text{a.e. in } \Omega \times [0, T_0] \times D,$$

$$j(u) + j^*(\xi) \in L^1(\Omega \times [0, T_0] \times D).$$

A generalized Itô formula for the square of the  $H$ -norm implies that  $u$  is càdlàg.

## Additive noise

Consider the problem

$$du + Au dt + \beta(u) dt \ni G dZ, \quad u(0) = u_0,$$

with  $G : \Omega \times [0, T_0] \rightarrow \mathcal{L}(K, H)$  predictable,  $\mathbb{E}\lambda_{T_0-}^C(G) < \infty$ ,  $\mathbb{E}\|u_0\|^2 < \infty$ .

Set  $G^\varepsilon := (I + \varepsilon A)^{-m} G$ , with  $m \in \mathbb{N}$  such that

$$G^\varepsilon \in L^0(\Omega; L^0(0, T_0; \mathcal{L}(K, V_0))), \quad \mathbb{E}\lambda_{T_0-}^C(G^\varepsilon) < \infty$$

(this is possible because a power of the resolvent of  $A_1$  is ultracontractive by assumption).

The regularized problem

$$du^\varepsilon + Au^\varepsilon dt + \beta(u^\varepsilon) dt \ni G^\varepsilon dZ, \quad u^\varepsilon(0) = u_0$$

has a unique solution by the previous results.

# Uniform estimates and passage to the limit as $\varepsilon \rightarrow 0$

By lower semicontinuity and estimates in expectation,

- ▶  $(u^\varepsilon)$  is bounded in  $L^2(\Omega; L^\infty(0, T_0; H)) \cap L^2(\Omega; L^2(0, T_0; V))$ ;
- ▶  $(\xi^\varepsilon)$  is relatively weakly compact in  $L^1(\Omega \times [0, T_0] \times D)$ .

Moreover, since

$$\mathbb{E} \|u^\varepsilon - u^\delta\|_{L^\infty(0, T_0; H) \cap L^2(0, T_0; V)}^2 \lesssim \mathbb{E} \lambda_{T_0-}^C (G^\varepsilon - G^\delta),$$

it follows that

- ▶  $(u^\varepsilon)$  is a Cauchy sequence in  $L^2(\Omega; L^\infty(0, T; H))$ .

Further lower semicontinuity arguments imply that  $(u, \xi)$  is the unique solution to the equation with additive noise.

The càdlàg property of  $u$  follows by uniform convergence.

# Localization

Let  $T$  be a finite stopping time. If  $C$  is a control process for  $Z$ , then  $C^{T-}$  is a control process for  $Z^{T-}$ . Considering the equation

$$dv + Av dt + \beta(v) dt = G dZ^{T-}, \quad v(0) = u_0,$$

one obtains the

**Lemma.** If  $G$  is predictable with  $\mathbb{E}\lambda_{T-}^C(G) < \infty$ , and  $\mathbb{E}\|u_0\|^2 < \infty$ , then  $(G)$  admits a unique strong solution on  $\llbracket 0, T \rrbracket$ .

The following continuity of  $(u_0, G) \mapsto u$  holds.

**Proposition.** Let  $u_i$  be solutions on  $\llbracket 0, T_i \rrbracket$  with data  $u_{0i}$  and  $G_i$ . Setting  $T := T_1 \wedge T_2$ , one has

$$\mathbb{E}(u_1 - u_2)_{T-}^{*2} + \mathbb{E} \int_0^T \|u_1 - u_2\|_V^2 \lesssim \mathbb{E}\|u_{01} - u_{02}\|^2 + \mathbb{E}\lambda_{T-}^C(G_1 - G_2).$$



## General case (multiplicative noise)

We can now treat the original problem

$$du + Au dt + \beta(u) dt = B(u-) dZ, \quad u(0) = u_0.$$

Let  $\alpha \in ]0, 1[$ ,  $R > 0$ , and

$$T^0 := \inf\{t \in [0, T_0] : C_t(L_t - L_0) \geq \alpha\} \wedge T_0, \quad T := T^0 \mathbb{1}_{\{\|u_0\| \leq R\}}.$$

Fixed point argument: let  $v \in \mathbb{S}^2(T_0-)$  and consider the problem

$$du + Au dt + \beta(u) dt \ni B(v-) dZ^{T-}, \quad u(0) = u_0,$$

which admits a unique strong solution, and

$$\|u_1 - u_2\|_{\mathbb{S}^2(T_0-)}^2 + \mathbb{E} \|u_1 - u_2\|_{L^2(0, T_0; V)}^2 \lesssim \alpha \|v_1 - v_2\|_{\mathbb{S}^2(T_0-)}^2.$$

Choosing  $\alpha$  small enough, we get a solution  $\tilde{u} \in \mathbb{S}^2(T_0-)$ . Now set

$$u := u_0 \mathbb{1}_{\{T=0\}} + \tilde{u} \quad \text{on } \llbracket 0, T \llbracket, \quad u_T = u_{T-} + B(\tilde{u}_{T-}) \Delta Z_T,$$

and  $\xi = \tilde{\xi} \mathbb{1}_{\llbracket 0, T \llbracket}$ . We have thus proved the

**Proposition.** There exists a stopping time  $T \neq 0$  and a strong solution on  $\llbracket 0, T \llbracket$ .

## General case (multiplicative noise)

Once local existence is established, one needs local uniqueness.

**Proposition.** If  $(u_i, \xi_i)$  is a local solution on  $\llbracket 0, T_i \rrbracket$ , then  $(u_i, \xi_i) = (u_j, \xi_j)$  on  $\llbracket 0, T_i \wedge T_j \rrbracket$ .

This follows by the continuity of  $(u_0, G) \mapsto u$ , further pre-stopping arguments, and a stochastic Gronwall inequality by Métivier.

One can now iterate the procedure used for local existence defining

$$T_{n+1} := \begin{cases} T_n, & \text{if } \|u_{T_n}\| > n, \\ \inf\{t \geq T_n : C_t(L_t - L_{T_n}) > \alpha\} \wedge T_0, & \text{if } \|u_{T_n}\| \leq n, \end{cases}$$

and show that  $\mathbb{P}(\lim_n T_n < T_0) = 0$  by linear growth of  $B$ .

Finally, the continuity of  $u_0 \mapsto u$  is obtained using continuity of  $(u_0, G) \mapsto u$  “prelocally” in  $\mathbb{S}^2$  and the stochastic Gronwall inequality.