Generic Lengths Spaces		
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ntroduction	Generic Properties of Lengths Space	
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# Baire Categories in Geometry

Generic Lengths Spaces

#### Introduction

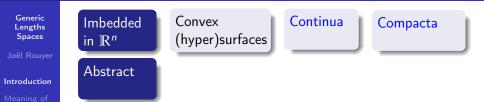
#### Convex Imbedded (hyper)surfaces

Abstract

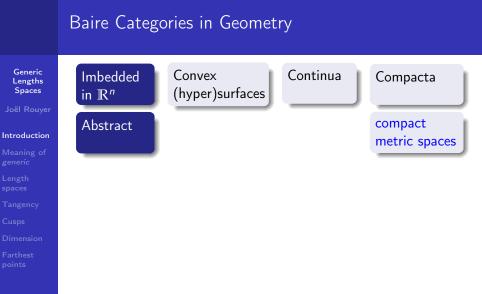
in  $\mathbb{R}^n$ 

- 1959: V. Klee, A generic C.S. is C<sup>1</sup> and strictly convex.
- 1977: P. Gruber, ... and not C<sup>2</sup>.
- 1979: R. Schneider, 1980,1988: T. Zamfirescu, 2012: K. Adiprasito and T. Zamfirescu, 2015: Schneider 2015. Study of directional curvature. (extrinsic property)
- 1982: T. Zamfirescu, A generic point is an endpoint.
- 1995: T. Zamfirescu, A generic point has a single farthest point, to whom it is joined by exactly 3 segments.
- 1988,91: P. Gruber, A generic C.S. has no (simple) closed geodesic. ◆□▶ ◆□▶ ◆□▶ ◆□▶ □ のQ@

# Baire Categories in Geometry



- 1988: J. A. Wieaker, Most compacta are homeomorphic to a cantor set.
- 1989: P. Gruber, generic dimension of compacta and continua.
- 1997: A. V. Kuz'minykh, Most compacta are totally anisometric : d(a, b) = d(a', b') > 0 ⇒ {a, b} = {a', b'}
- 1989–2005: Results on the embedding: E.S. De Blasi, P. Gruber, J. Myjak & R. Rudnick, J. A. Wieaker, T. Zamfirescu, N.V. Zhivkov.



• 2011: J. Rouyer.

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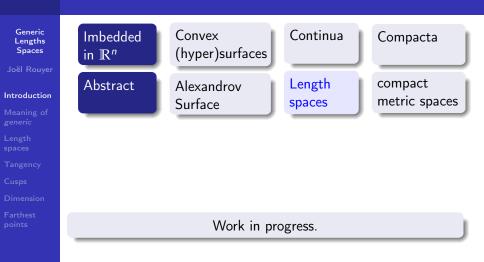
# Baire Categories in Geometry



- Length spaces
- Tangency
- Cusps
- Dimension
- Farthest points

- 2012: K. Adiprazito and T. Zamfirecu, Most points are endpoints.
- 2015: J.-I. Itoh, J. R. , C. Vîlcu, No conical points, but no Gaussian curvature.
- 2016: J. R., C. Vîlcu, No/infinitely many simple closed geodesic, depending on the curvature bound and the connected component of the space.

# Baire Categories in Geometry



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# Baire Categories

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Farthest points Let X be a topological space.

- $R \subset X$  is rare or nowhere dense iff int  $(cl(R)) = \emptyset$ .
- *M* ⊂ *X* is meager or of first category iff it is included in a countable union of rare sets.
- X is a Baire space iff any meager set have empty interior.
- The Baire's theorem states that any complete metric space is a Baire space.

#### Convention

We say that

- most  $x \in X$  are . . .
- or that a generic  $x \in X$  is ...

to express that the set of those  $x \in X$  which are not ... form a meager set in X.

# Length spaces I

#### Generic Lengths Spaces

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#### Preliminary Remark

During this talk, a *length space* is supposed to be compact. (unlike most authors)

### Definition

Let 
$$\gamma: [a, b] \to X$$
. The length of  $\gamma$  is

$$L(\gamma) = \sup_{(t_0,\ldots,t_n)\in S} \sum_{i=1}^n d(\gamma(t_{i-1}),\gamma(t_i)),$$

where  $S = \{(t_0, ..., t_n) \in \mathbb{R}^n | n \in \mathbb{N}, a = t_0 < t_1 < ... < t_n = b\}$ 

# Length spaces II

#### Generic Lengths Spaces

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#### Theorem

Let X be a compact metric space. Denote by  $\Gamma(x, y)$  the set of curves from x to y. The following statements are equivalent:

- existence of segments:  $\forall x, y \in X \exists \gamma \in \Gamma(x, y) \ s.t.$  $d(x, y) = L(\gamma).$
- existence of midpoints:  $\forall x, y \in X \exists z \in X \ s.t.$

$$d(x,z) = d(z,y) = \frac{1}{2}d(x,y).$$

• intrinsic metric:  $\forall x, y \in X, d(x, y) = \inf_{\gamma \in \Gamma(x, y)} L(\gamma).$ 

#### Definition

A compact metric space satisfying these properties is called a (compact) length space. The set of length spaces is denoted by  $\mathcal{L}$ .

# Length spaces III Examples

Generic Lengths Spaces

# (Counter)example

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# $\{x \in \mathbb{R}^2 | ||x|| = 1\}$ endowed with the metric $d_0(x, y) = ||x - y||$ is not a length space, but endowed with $d_1(x, y) = \arccos \langle x, y \rangle$ is a length space.

#### Example

$$\mathbb{R}^2 / \mathbb{Z}^2 \text{ endowed with} d((x_1, y_1), (x_2, y_2)) = \min(|x_1 - x_2|, 1 - |x_1 - x_2|) + \min(|y_1 - y_2|, 1 - |y_1 - Y_2|).$$

### Example

More generally, any reversible (compact) Finsler manifold, and so any (compact) Riemannian manifold.

# Length space IV Finite metric graphs



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- Start with a finite combinatorial graph: (V, E), E ⊂ P<sub>2</sub>(V) × N
- Assign lengths to edges: choose  $\lambda: E \rightarrow ]0, +\infty[$

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# Length space IV Finite metric graphs

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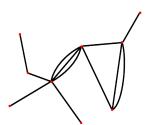
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- Start with a finite combinatorial graph: (V, E), E ⊂ P<sub>2</sub>(V) × IN
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• The set of points is  $G = V \cup ]0, 1[\times E]$ 

# Length space IV Finite metric graphs

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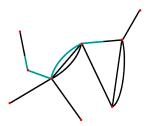
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- Start with a finite combinatorial graph:  $(V, E), E \subset \mathcal{P}_2(V) \times \mathbb{N}$
- Assign lengths to edges: choose  $\lambda: E \rightarrow ]0, +\infty[$

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- The set of points is  $G = V \cup ]0, 1[\times E]$
- Define the length of a simple path:  $\ell_{\mathcal{G}}(\gamma) = \sum_{\Delta \in E} \lambda(\delta) \ell_{]0,1[}(\gamma_{E})$ , where  $\gamma_{E} = \gamma \cap E$ .

# Length space IV Finite metric graphs

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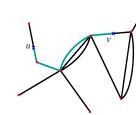
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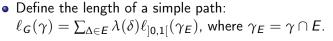


- Start with a finite combinatorial graph:  $(V, E), E \subset \mathcal{P}_2(V) \times \mathbb{N}$
- Assign lengths to edges: choose  $\lambda: E \rightarrow ]0, +\infty[$

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• The set of points is  $G = V \cup ]0, 1[\times E]$ 



 Define d(u, v) = inf<sub>γ</sub>ℓ(γ), where the infimum is taken over all the simple paths γ from u to v.

Any finite metric graph is a length space, We denote by  $\mathcal{G}$  the set of finite metric graphs.

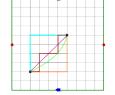
# Length space V Geodesics in length spaces

#### Generic Lengths Spaces

### Definition

# A geodesic is a path which is locally a segment.

#### Length spaces



Finsler torus  $\mathbb{R}^2/\mathbb{Z}^2$  endowed with  $|| ||_1$ .

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- Geodesics may branch.
- No injectivity radius.

# Length space V Geodesics in length spaces

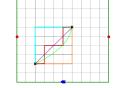
#### Generic Lengths

#### Definition

# Spaces

# A geodesic is a path which is locally a segment.

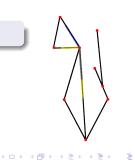
#### Length spaces



Finsler torus  $\mathbb{R}^2/\mathbb{Z}^2$  endowed with || ||1.

# A metric graph.

- Geodesics may branch.
- No injectivity radius.
- Geodesics may stop.
- Existence of *endpoints*.

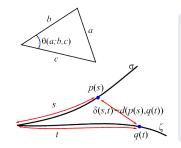


# Length space VI Angles in length spaces 1

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One can define *lower* and *upper angles* between segments.

$$\underline{\measuredangle}(\sigma,\zeta) = \liminf_{s,t\to 0} \theta(\delta(s,t);s,t)$$

$$\overline{\measuredangle}(\sigma,\zeta) = \limsup_{s,t\to 0} \theta(\delta(s,t);s,t)$$

- When the two angles agree, we say that the segments make a well-defined angle.
- In Alexandrov spaces, all angle are well-defined.
- In Riemannian manifold, this notion of angles is equivalent to the usual one.

## Length space VII Angles in length spaces 2

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For instance, in 
$$(\mathbb{R}^2/\mathbb{Z}^2, || ||_1)$$
, the angles  
between  $\sigma : Y = 0$  and  $\zeta : Y = aX$  are  
 $\underline{\measuredangle}(\sigma, \zeta) = 0$ ,  
 $\overline{\measuredangle}(\sigma, \zeta) = \arccos\left(\frac{1-a}{1+a}\right)$ .



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 $\underline{\sigma}_1 \underline{\sigma}_2$ 

In any length space, if  $\sigma_1$  and  $\sigma_2$  are two parts of a same segment then  $\underline{\measuredangle}(\sigma_1, \sigma_1) = \overline{\measuredangle}(\sigma_1, \sigma_1) = 0,$  $\underline{\measuredangle}(\sigma_1, \sigma_2) = \overline{\measuredangle}(\sigma_1, \sigma_2) = \pi.$ 

# Space of length spaces I The Gromov-Hausdorff metric

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## Notation. Let Z be a metric space.

•  $\mathcal{K}(Z)$  denotes the set of nonempty compact subsets of Z

• for 
$$A \in \mathcal{K}(Z)$$
 and  $\rho \in \mathbb{R}_+$ ,  
 $A + \rho \stackrel{\text{def}}{=} \{ y \in Z \mid \exists x \in A \text{ s.t. } d(x, y) \le \rho \}$ 

#### Definition

• for A,  $B \in \mathcal{K}(Z)$ , the Pompeiu-Hausdorff distance is:

$$d_{PH}^{Z}(A, B) = \inf \left\{ \varepsilon \mid A \subset B + \varepsilon, B \subset A + \varepsilon \right\}$$

• for X, Y compact metric spaces, the Gromov-Hausdorff distance is:  $d_{GH}(X, Y) = \inf_{Z, f, g} d_{PH}^{Z}(f(X), g(Y)),$ 

where the infimum is taken over all metric spaces Z and all isometric embeddings  $f : X \to Z$ ,  $g : Y \to Z$ .

# Space of Length spaces II

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#### Theorem

The set  $\mathcal{GH}$  of all compact metric spaces, up to isometries, endowed with  $d_{GH}$  is a complete metric space.

#### Theorem

 ${\cal L}$  is closed in  ${\cal GH}$  and so, is a complete metric space.

#### Theorem

 ${\cal G}$  is dense in  ${\cal L}$ .

#### Theorem

The set of Riemannian surfaces is dense in  $\mathcal{L}$ .

# Definition of *f*-tangency I

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#### motivation

- No differential structure
- No angle

#### Definition

A comparison function is smooth increasing function  $f: ]0, \infty[\rightarrow]0, \infty[ s.t. f(x) = o(x)$  when x goes to 0.

#### Notation

The set of segments emanating from a point x will be denoted by  $\Sigma_x.$ 

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# Definition of f-tangency II

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### Definition

- Let f be a comparison function,  $\sigma, \gamma \in \Sigma_x$ 
  - σ, γ are said to be weakly f-tangent if there exists a sequence of positive numbers t<sub>n</sub> tending to 0 such that σ(t<sub>n</sub>) γ(t<sub>n</sub>) < f(t<sub>n</sub>).
  - **2**  $\sigma$ ,  $\gamma$  are said to be f-tangent if there exists  $\tau > 0$  such that for any  $t \in [0, \tau] \sigma(t) \gamma(t) \leq f(t)$ .
  - σ, γ are said to be strongly f-tangent if there exists τ > 0 such that for any s, t ∈ [0, τ]
     σ(t) γ(s) ≤ |s − t| + f (min (s, t)).

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# *f*-tangency and angles

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#### Proposition

# For any comparison function f,

- If  $\sigma, \gamma \in \Sigma_x$  are strongly f-tangent then  $\overline{\measuredangle}(\sigma, \gamma) = 0$ .
- 2 If  $\sigma, \gamma \in \Sigma_x$  are weakly f-tangent then  $\underline{\measuredangle}(\sigma, \gamma) = 0$ .

#### Theorem

Let f be a comparison function. For most  $X \in \mathcal{L}$ , if  $\sigma$ ,  $\gamma \in \Sigma_x$  are f-tangent, then either  $\sigma \subset \gamma$  or  $\gamma \subset \sigma$ .

#### Corollary

In a generic length space geodesics do not bifurcate.

# A generic result about angles

#### Generic Lengths Spaces

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# In a generic length space, at any point x, any two segments $\sigma, \gamma \in \Sigma_x$ satisfy $\underline{\measuredangle}(\sigma, \gamma) = 0$ or $\overline{\measuredangle}(\sigma, \gamma) = \pi$ .

#### Problem

Theorem

• How common/rare are the pairs  $(\sigma, \gamma) \in \Sigma_x^2$  such that  $\underline{\measuredangle}(\sigma, \gamma) = 0$  and  $\underline{\measuredangle}(\sigma, \gamma) = \pi$ ?

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• How common/rare are the pairs of segments with a well-defined angle ?

# Definition of *f*-cusp

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#### Definition

Let f be a comparison function. If  $x \in X \in \mathcal{L}$  is such that any two segments  $\sigma, \gamma$  emanating from x are (resp. weakly, resp. strongly) tangent we call x a (resp. weak, resp. strong) f-cusp.

#### Example

If  $X \in G$ , its (weak/strong) f-cusp are exactly its endpoints.

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# Cusp properties

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#### Proposition

**1** A strong f-cusp is a f-cusp.

**2** A f-cusp is a weak  $\lambda$ f-cusp for any  $\lambda > 1$ .

#### Proposition

A weak f-cusp is interior to no segment.

#### Theorem

Let f be a comparison function. In a generic length space,

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there is no f-cusp,

2 a generic point  $x \in X$  is a weak f-cusps.

### Dimensions The many names dimension

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Farthest points Names are: box dimension, box-counting  $\sim$ , capacity  $\sim$ , fractal  $\sim$ , Kolmogorov  $\sim$ , Minkowski  $\sim$ , Minkowski-Bouligand, ...

#### Notation

• 
$$N(X,\varepsilon) = \min \{ \operatorname{card}(F) | F \subset X \ \forall x \in X \ d(x,F) \le \varepsilon \}$$
  
•  $M(X,\varepsilon) = \max \left\{ \operatorname{card}(F) \begin{vmatrix} F \subset X \ \text{and} \\ \forall x, y \in F \ x \neq y \Rightarrow xy \ge \varepsilon \end{vmatrix} \right\}$ 

#### Theorem and definition

The *upper* and *lower box dimension* of a compact metric space X are defined as

$$\dim^{B} (X) = \limsup_{\varepsilon \to 0} \frac{\log N(X, \varepsilon)}{-\log \varepsilon} = \limsup_{\varepsilon \to 0} \frac{\log M(X, \varepsilon)}{-\log \varepsilon}$$
$$\dim_{B} (X) = \liminf_{\varepsilon \to 0} \frac{\log N(X, \varepsilon)}{-\log \varepsilon} = \liminf_{\varepsilon \to 0} \frac{\log M(X, \varepsilon)}{-\log \varepsilon}.$$

# Generic dimension

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# $\dim_{\mathcal{T}} \leq \dim_{\mathcal{H}} \leq \dim_{\mathcal{B}} \leq \dim^{\mathcal{B}}$

#### Theorem

Let X be a generic length space.

• dim<sub>B</sub>(X) = 1 and dim<sup>B</sup>(X) = 
$$\infty$$
.

• 
$$\mathcal{H}^1(X) = \infty$$

#### Theorem

In a generic compact length space,  $\forall x \in X, \forall \rho > 0, \dim_B(S_x(\rho)) = 0.$ 

#### Question

What can one say (generically) of  $\dim^B S_x(\rho)$  ?

#### Notation

For  $x \in X \in \mathcal{L}$ ,  $S_x(\rho)$  is the sphere centred at x with radius  $\rho$ , that is  $\{y \in X | d(x, y) = \rho\}$ 

# Farthest points

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#### Notation

$$ho_x = max_{y \in X} d(x, y)$$
  
 $F_x = S_x(
ho_x)$ 

#### Theorem

For a generic  $X \in \mathcal{L}$  and a generic  $x \in X$ ,  $card(F_x) = 1$ .

# Farthest points

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#### Notation

$$egin{aligned} & \rho_x = \max_{y \in X} d(x,y) \ & F_x = S_x(
ho_x) \end{aligned}$$

For a generic  $X \in \mathcal{L}$  and a generic  $x \in X$ ,  $card(F_x) = 1$ .

Embedded in $\mathbb{R}^n$	Convex surfaces T.Z. (1995)	Continua ?	Compacta Kuz'minykh (1997)
Abstract	Alex. Surfaces	Length	compact
	J.R & C.V.	spaces	metric spaces
	(2018?)	J.R.(2019?)	J.R. (2011)

# Proof I Preliminary

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#### Theorem

On a compact manifold endowed with a generic Riemannian structure, a generic point has a single farthest point.

J. Rouyer (2003).

#### Lemma

The function F is upper semi-continuous, that is

 $\lim_{x\to x_0}F_x\subset F_{x_0}.$ 

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# Proof II

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# Denote by $\delta(A)$ the diameter of A.

$$\mathcal{M} \stackrel{\text{def}}{=} \{X \mid \{x \in X \mid \#F_x > 1\} \text{ non meager}\} \\ = \bigcup_p \{X \mid \text{int}\{x \in X \mid \delta(F_x) \ge 1/p\} \neq \emptyset\} \\ = \bigcup_p \bigcup_q \left\{X \mid \exists y \in X \ \bar{B}\left(y, \frac{1}{q}\right) \subset \{x \in X \mid \delta(F_x) \ge 1/p\}\right\} \\ \stackrel{\text{def}}{=} \bigcup_p \bigcup_q \mathcal{M}_{pq}.$$

- $\mathcal{M}_{pq}$  has empty interior.
- It remains to prove that it is closed.

# Proof III

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$$\mathcal{M}_{pq} = \left\{ X \left| \exists y \in X \ \bar{B}\left(y, \frac{1}{q}\right) \subset \left\{x \in X \left| \delta\left(F_x\right) \ge 1/p\right\} \right\} \right\}$$

•  $\mathcal{M}_{pq} \ni X_n \in \mathcal{M}_{pq} \xrightarrow{\rightarrow} X \in \mathcal{L}.$ • W.I.g., we can assume that  $X_n, X \subset Z$  and  $X_n \xrightarrow{\rightarrow}_{DH} X$ . • Take  $y_n \in X_n$  s.t.  $\bar{B}\left(y_n, \frac{1}{q}\right) \subset \left\{x \in X_n | \delta\left(F_x\right) \ge 1/p\right\}$ • Take a converging sub-sequence; let  $y \in X$  be the limit. • We claim that  $\bar{B}\left(y, \frac{1}{q}\right) \subset \{x \in X_n | \delta\left(F_x\right) \ge 1/p\}$ , and so,  $X \in \mathcal{M}_{pq}$ . •  $z \in \overline{B}\left(y, \frac{1}{a}\right) \leftarrow z_n \in \overline{B}\left(y_n, \frac{1}{a}\right) \subset \left\{x \in X_n \left|\delta(F_x) \geq \frac{1}{a}\right\}\right\}$ •  $\delta(F_{z_n}) \geq \frac{1}{n}$ . • By semi-continuity of F,  $\delta(F_z) > \frac{1}{2}$ 

• 
$$z \in \left\{ x \in X \mid \delta(F_x) \ge \frac{1}{p} \right\}$$

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Farthest points Thank you very much for your attention !

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