# SOME GEOMETRICAL ASPECTS OF THE Г-CORRELATED PROCESSES 

ILIE VALUSESCU


#### Abstract

Some geometrical aspects of the $\Gamma$-correlated processes are analyzed, starting from the properties of a $\Gamma$-orthogonal projection, which is not a proper one. Geometrical results are generalized to $\Gamma$-correlated case, especially the problem of the angle between the past and the future of some $\Gamma$-correlated processes. In the periodically $\Gamma$-correlated case it is proved that the positivity of the angle is preserved by its stationary dilation process. The generalized Friedrichs angle and other geometrical concepts are used in analysing some properties of periodically $\Gamma$-correlated processes.


## 1. Preliminaries

A $\Gamma$-correlated process is a sequence $\left(f_{t}\right)_{t \in G}$ in a right $\mathcal{L}(\mathcal{E})$-module $\mathcal{H}$ endowed with a correlation of the action of $\mathcal{L}(\mathcal{E})$. The set $G$ is $\mathbb{Z}, \mathbb{R}$, or more generally a locally compact abelian group, and by $\mathcal{L}(\mathcal{E})$ is denoted the $C^{*}$-algebra of all linear bounded operators on a separable Hilbert space $\mathcal{E}$. In this paper mainly the discrete case $G=\mathbb{Z}$ is considered.

By an action of $\mathcal{L}(\mathcal{E})$ on $\mathcal{H}$ we mean the map $\mathcal{L}(\mathcal{E}) \times \mathcal{H}$ into $\mathcal{H}$ given by $A h:=h A$ in the sense of the right $\mathcal{L}(\mathcal{E})$-module $\mathcal{H}$. We are writting $A h$ instead of $h A$ to respect the classical notations from the scalar case. A correlation of the action of $\mathcal{L}(\mathcal{E})$ on $\mathcal{H}$ is a map $\Gamma$ from $\mathcal{H} \times \mathcal{H}$ into $\mathcal{L}(\mathcal{E})$ having the properties:
(i) $\Gamma[h, h] \geq 0$, and $\Gamma[h, h]=0$ implies $h=0$;
(ii) $\Gamma[h, g]^{*}=\Gamma[g, h]$;
(iii) $\Gamma[h, A g]=\Gamma[h, g] A$.

In many proofs it is very useful the formula

$$
\Gamma\left[\sum_{i} A_{i} h_{i}, \sum_{j} B_{j} g_{j}\right]=\sum_{i, j} A_{i}^{*} \Gamma\left[h_{i}, g_{j}\right] B_{j}
$$

obtained by (ii) and (iii) for finite sums of actions of $\mathcal{L}(\mathcal{E})$ on $\mathcal{H}$.
A triplet $\{\mathcal{E}, \mathcal{H}, \Gamma\}$ defined as above was called $[12,13]$ a correlated action of $\mathcal{L}(\mathcal{E})$ on $\mathcal{H}$.
By the fact that generally in $\mathcal{H}$ we have no topology, the prediction subsets, such as past and present, future, etc., can not be seen as closed subspaces, therefore the powerful tool of the orthogonal projection can not be directly used.

An example of correlated action can be constructed as follows. Take as the right $\mathcal{L}(\mathcal{E})$ module $\mathcal{H}=\mathcal{L}(\mathcal{E}, \mathcal{K})$ - the space of the linear bounded operators from $\mathcal{E}$ into $\mathcal{K}$, where $\mathcal{E}$ and $\mathcal{K}$ are Hilbert spaces. An action of $\mathcal{L}(\mathcal{E})$ on $\mathcal{L}(\mathcal{E}, \mathcal{K})$ is given if we consider $A V:=V A$ for each $A \in \mathcal{L}(\mathcal{E})$ and $V \in \mathcal{L}(\mathcal{E}, \mathcal{K})$. It is easy to see that $\Gamma\left[V_{1}, V_{2}\right]=V_{1}^{*} V_{2}$ is a correlation of the action of $\mathcal{L}(\mathcal{E})$ on $\mathcal{L}(\mathcal{E}, \mathcal{K})$, and the triplet $\{\mathcal{E}, \mathcal{L}(\mathcal{E}, \mathcal{K}), \Gamma\}$ is a correlated action (the

[^0]operator model). It was proved [12] that any abstract correlated action $\{\mathcal{E}, \mathcal{H}, \Gamma\}$ can be embedded into the operator model. Namely, there exists an algebraic embedding $h \rightarrow V_{h}$ of $\mathcal{H}$ into $\mathcal{L}(\mathcal{E}, \mathcal{K})$, where $\mathcal{K}$ is obtained as the Aronsjain reproducing kernel Hilbert space given by a positive definite kernel obtained from the correlation $\Gamma$. The generators of $\mathcal{K}$ are elements of the form $\gamma_{(a, h)}: \mathcal{E} \times \mathcal{H} \rightarrow \mathbb{C}$, where $\gamma_{(a, h)}(b, g)=\langle\Gamma[g, h] a, b\rangle_{\mathcal{E}}$ and the embedding $h \rightarrow V_{h}$ is given by $V_{h} a=\gamma_{(a, b)}$.

Due to such an embedding of any correlated action $\{\mathcal{E}, \mathcal{H}, \Gamma\}$ into the operator model, prediction problems can be formulated and solved using operator techniques. In the particular case when the embedding $h \rightarrow V_{h}$ is onto, the correlated action $\{\mathcal{E}, \mathcal{H}, \Gamma\}$ is caled a complete correlated action. In this paper most of properties are analysed in the complete correlated case.

## 2. Some geometrical aspects

A first geometrical aspect is the existence of a $\Gamma$-orthogonal projection "on" a right $\mathcal{L}(\mathcal{E})$ submodule $\mathcal{H}_{1}$ of $\mathcal{H}$.

Proposition 2.1. Let $\mathcal{H}_{1}$ be a submodule in the right $\mathcal{L}(\mathcal{E})$-module $\mathcal{H}$ and

$$
\begin{equation*}
\mathcal{K}_{1}=\bigvee_{x \in \mathcal{H}_{1}} V_{x} \mathcal{E} \subset \mathcal{K} \tag{2.1}
\end{equation*}
$$

For each $h \in \mathcal{H}$ there exists a unique element $h_{1} \in \mathcal{H}$ such that for each $a \in \mathcal{E}$ we have

$$
\begin{equation*}
V_{h_{1}} a \in \mathcal{K}_{1} \quad \text { and } \quad V_{h-h_{1}} a \in \mathcal{K}_{1}^{\perp} . \tag{2.2}
\end{equation*}
$$

Moreover, we have

$$
\begin{equation*}
\Gamma\left[h-h_{1}, h-h_{1}\right]=\inf _{x \in \mathcal{H}_{1}} \Gamma[h-x, h-x], \tag{2.3}
\end{equation*}
$$

where the infimum is taken in the set of all positive operators from $\mathcal{L}(\mathcal{E})$.
A complete proof can be found in [12]. This result assure that if we put

$$
\begin{equation*}
\mathcal{P}_{\mathcal{H}_{1}} h=h_{1}, \tag{2.4}
\end{equation*}
$$

then we can interpret the endomorphism $\mathcal{P}_{\mathcal{H}_{1}}$ of $\mathcal{H}$ as a $\Gamma$-orthogonal projection "on" $\mathcal{H}_{1}$, since we have $\mathcal{P}_{\mathcal{H}_{1}}^{2}=\mathcal{P}_{\mathcal{H}_{1}}$ and $\Gamma\left[\mathcal{P}_{\mathcal{H}_{1}} h, g\right]=\Gamma\left[h, \mathcal{P}_{\mathcal{H}_{1}} g\right]$.

As a geometrical aspect, let us remark that the unique element $h_{1}$ obtained by the $\Gamma$ orthogonal projection of $h \in \mathcal{H}$ can belongs not necessary to $\mathcal{H}_{1}$, but, due to (2.3) it is close enough to be considered as the best estimation.

The previous result can be generalized to an "orthogonal projection" from $\mathcal{H}^{T}$ - the cartesian product of $T$ copies of $\mathcal{H}$ on a submodule $\mathcal{M}$ of $\mathcal{H}^{T}$, as follows. Firstly, the embedding of $\mathcal{H}^{T}$ into $\mathcal{L}\left(\mathcal{E}, \mathcal{K}^{T}\right)$ is defined by

$$
\begin{equation*}
W_{X} a=\left(V_{x_{1}} a, \ldots, V_{x_{T}} a\right) \tag{2.5}
\end{equation*}
$$

for $a \in \mathcal{E}$ and $X=\left(x_{1}, \ldots, x_{T}\right) \in \mathcal{H}^{T}$, and then the extended "orthogonal projection" $\mathcal{P}_{\mathcal{M}} X$ it follows with respect to an appropriate correlation [15], considering $\mathcal{K}_{1}^{T}=\bigvee_{X \in \mathcal{M}} W_{X} \mathcal{E}$ in $\mathcal{K}^{T}$ 。

The action of $\mathcal{L}(\mathcal{E})$ on $\mathcal{H}^{T}$ is given by acting on the components, which is a particular case of the matrix action of $\mathcal{L}(\mathcal{E})^{T \times T}$ on $\mathcal{H}^{T}$ in the sense of the right multiplication.

A $\Gamma$-correlated process $\left(f_{t}\right) \subset \mathcal{H}$ is stationary if $\Gamma\left[f_{s}, f_{t}\right]$ depends only on $t-s$ and not by $s$ and $t$ separately. For a $\Gamma$-correlated process (not necessary stationary) the past-present at the moment $t=n$ is the right $\mathcal{L}(\mathcal{E})$-submodule

$$
\begin{equation*}
\mathcal{H}_{n}^{f}=\left\{\sum_{k} A_{k} f_{k} ; A_{k} \in \mathcal{L}(\mathcal{E}), k \leq n\right\}, \tag{2.6}
\end{equation*}
$$

the future is

$$
\begin{equation*}
\widetilde{\mathcal{H}}_{n}^{f}=\left\{\sum_{k} A_{k} f_{k} ; A_{k} \in \mathcal{L}(\mathcal{E}), k>n\right\}, \tag{2.7}
\end{equation*}
$$

and the time domain is

$$
\mathcal{H}_{\infty}^{f}=\left\{\sum_{k} A_{k} f_{k} ; A_{k} \in \mathcal{L}(\mathcal{E}), k \in \mathbb{Z}\right\} .
$$

By the embedding $h \rightarrow V_{h}$ of $\mathcal{H}$ into $\mathcal{L}(\mathcal{E}, \mathcal{K})$, for the corresponding past and future from $\mathcal{H}$ will correspond the closed subspaces of $\mathcal{K}$ given by

$$
\begin{align*}
\mathcal{K}_{n}^{f} & =\bigvee_{j \leq n} V_{f_{j}} \mathcal{E},  \tag{2.8}\\
\widetilde{\mathcal{K}}_{n}^{f} & =\bigvee_{j>n} V_{f_{j}} \mathcal{E}, \tag{2.9}
\end{align*}
$$

respectively, and the time domain becomes

$$
\mathcal{K}_{\infty}^{f}=\bigvee_{j \leq n} V_{f_{j}} \mathcal{E}
$$

Various processes can be considered in the right $\mathcal{L}(\mathcal{E})$-module, or $\mathcal{L}(\mathcal{E})^{T \times T}$-module $\mathcal{H}^{T}$, and appropriate past and future constructed. Also, various correlations can be done. For the study of periodically correlated processes, the following correlations are of interest. For $X=\left(x_{1}, \ldots, x_{T}\right)$ and $Y=\left(y_{1}, \ldots, y_{T}\right)$ from $\mathcal{H}^{T}$, taking into account the right action of $\mathcal{L}(\mathcal{E})$, respectively of $\mathcal{L}(\mathcal{E})^{T \times T}$ on $\mathcal{H}^{T}$, it is simply to see that $\Gamma_{1}: \mathcal{H}^{T} \times \mathcal{H}^{T} \rightarrow \mathcal{L}(\mathcal{E})$ and $\Gamma_{T}: \mathcal{H}^{T} \times \mathcal{H}^{T} \rightarrow \mathcal{L}(\mathcal{E})^{T \times T}$ defined, respectively, by

$$
\begin{equation*}
\Gamma_{1}[X, Y]=\sum_{k=1}^{T} \Gamma\left[x_{k}, y_{k}\right] \tag{2.10}
\end{equation*}
$$

and the matriceal one

$$
\begin{equation*}
\Gamma_{T}[X, Y]=\left(\Gamma\left[x_{i}, y_{j}\right]\right)_{i, j \in\{1,2, \ldots, T\}} \tag{2.11}
\end{equation*}
$$

are correlations on $\mathcal{H}^{T}$.
Remember that a process $\left(f_{t}\right)$ is periodically $\Gamma$-correlated if there exists a positive $T$ such that $\Gamma\left[f_{s+T}, f_{t+T}\right]=\Gamma\left[f_{s}, f_{t}\right]$.

For a $\Gamma$-correlated process $\left(f_{t}\right)$, if we take sequences of consecutive $T$ terms

$$
\begin{equation*}
X_{n}=\left(f_{n}, f_{n+1}, \ldots, f_{n+T-1}\right), \tag{2.12}
\end{equation*}
$$

then $\left(X_{n}\right)$ is a stationary $\Gamma_{1}$-correlated process in $\mathcal{H}^{T}$. Taking consecutive blocks of length $T$

$$
\begin{equation*}
X_{n}^{T}=\left(f_{n T}, f_{n T+1}, \ldots, f_{n T+T-1}\right) \tag{2.13}
\end{equation*}
$$

then $\left(X_{n}^{T}\right)$ is a stationary $\Gamma_{T}$-correlated process in $\mathcal{H}^{T}$.
From prediction point of view and the study of periodically $\Gamma$-correlated processes, the following result [15] was proved.

Proposition 2.2. Let $\left(f_{n}\right)_{n \in \mathbb{Z}}$ be a $\Gamma$-correlated process in $\mathcal{H}, T \geq 2$, $\left(X_{n}\right)$ and $\left(X_{n}^{T}\right)$ defined by (2.12) and (2.13). The following are equivalent:
(i) $\left\{f_{n}\right\}$ is periodically $\Gamma$-correlated in $\mathcal{H}$, with the period $T$;
(ii) $\left\{X_{n}\right\}$ is stationary $\Gamma_{1}$-correlated in $\mathcal{H}^{T}$;
(iii) $\left\{X_{n}^{T}\right\}$ is stationary $\Gamma_{T}$-correlated in $\mathcal{H}^{T}$.

Between other strong geometrical aspects, such as the Wold decomposition of a $\Gamma$ correlated process, the dilation of a nonstationary process to a stationary one is very useful for prediction resons. A nonstatioary $\Gamma$-correlated process $\left(f_{t}\right)$ in $\mathcal{H}$ has a stationary dilation if there exists a larger right module $H$ and a stationary process $\left(g_{t}\right)$ in $H$ such that $f_{t}=\mathcal{P}_{\mathcal{H}}^{H} g_{t}$. It is easy to see that each periodically $\Gamma$-correlated process $\left(f_{t}\right) \subset \mathcal{H}$ has a stationary $\Gamma_{1}$-correlated dilation $\left(X_{n}\right) \subset \mathcal{H}^{T}$ given by (2.12).

The geometrical property of a process to have a stationary dilation permits us to use some stationary techniques in the study of some nonstationary processes. This is the case at least for the processes very close to the stationary processes, such as periodically, harmonizable, or uniformly bounded linearly stationary processes.

A nice geometrical aspect is the fact that in the discrete case $(G=\mathbb{Z})$ each periodically $\Gamma$-correlated process with the period $T$ is $\Gamma$-harmonizable and its spectral distribution is an $\mathcal{L}(\mathcal{E})$-valued semispectral measure supported on $2 T-1$ equidistant stright line segments parallel to the diagonal of the square $[0,2 \pi] \times[0,2 \pi]$. Unfortunately this nice property is not generally valid when $G=\mathbb{R}$, even under some continuity conditions. The stationarity is characterized by the fact that the support is reduced to the diagonal.

## 3. The angle between past and future

One of the prediction problem is the study of the angle between the past and the future of a process. Starting with the studies of Helson and Szegő [7] and Helson and Sarason [8], the results was generalized in various contexts, helping in the characterization of stationary and some nonstationary processes. Here a generalization in the stationary $\Gamma$-correlated case is obtained, and some results for periodically case are analyzed.

Actually the notions of the angles between two subspaces of a Hilbert space arise in [4] and [3], starting from the general definition of the scalar product of two vectors into the form $\langle h, g\rangle=\|h\|\|g\| \cdot \cos \alpha$. The angle (sometimes called the Dixmier angle) between two subspaces $\mathcal{M}$ and $\mathcal{N}$ of a Hilbert space $\mathcal{K}$ is given by its cosine

$$
\begin{equation*}
\rho(\mathcal{M}, \mathcal{N}):=\sup \left\{|\langle h, g\rangle| ; h \in \mathcal{M} \cap B_{\mathcal{K}}, g \in \mathcal{N} \cap B_{\mathcal{K}}\right\} . \tag{3.1}
\end{equation*}
$$

where $B_{\mathcal{K}}$ is the unit ball of $\mathcal{K}$.
In the context of a complete correlated action $\{\mathcal{E}, \mathcal{H}, \Gamma\}$ the cosine between the submodules $\mathcal{M}$ and $\mathcal{N}$ of the right $\mathcal{L}(\mathcal{E})$-module $\mathcal{H}$ is given by

$$
\rho(\mathcal{M}, \mathcal{N})=\sup \{|\langle\Gamma[g, h] a, b\rangle| ;\|\Gamma[h, h] a\| \leq 1,\|\Gamma[g, g] b\| \leq 1\},
$$

where $h \in \mathcal{M}, g \in \mathcal{N}, a, b \in \mathcal{E}$.
We say that $\mathcal{M}$ and $\mathcal{N}$ have a positive angle if $\rho(\mathcal{M}, \mathcal{N})<1$, or equivalently, if there exists $\rho<1$ such that for any $h \in \mathcal{M}, g \in \mathcal{N}, a, b \in \mathcal{E}$

$$
\begin{equation*}
\left|\langle\Gamma[g, h] a, b\rangle_{\mathcal{E}}\right| \leq \rho\left\|V_{h} a\right\|\left\|V_{g} b\right\| . \tag{3.2}
\end{equation*}
$$

In the study of prediction problems we are interested in the case when the angle between past and future is positive, i.e., when $\rho(n)=\rho\left(\mathcal{H}_{n}^{f}, \widetilde{\mathcal{H}}_{n}^{f}\right)<1$, which will give the possibility of finding the predictor.

A nice geometrical aspect of stationary $\Gamma$-correlated process is the fact that the angle between the past and future is constant.

Proposition 3.1. If $\left(f_{n}\right)$ is a stationary $\Gamma$-correlated process in $\mathcal{H}$, then the angle between the past and future does not depends on the choosing of the present time $t=n$.

Proof. Indeed, for $a, b \in \mathcal{E}$, at the moment $t=n$ we have

$$
\rho(n)=\sup \left\{|\langle\Gamma[g, h] a, b\rangle| ; h \in \mathcal{H}_{n}^{f}, g \in \widetilde{\mathcal{H}}_{n}^{f}\right\}=
$$

$$
\begin{aligned}
& =\sup \left\{\left|\left\langle\Gamma\left[\sum_{k>n} A_{k} f_{k}, \sum_{p \leq n} A_{p} f_{p}\right] a, b\right\rangle\right| ; A_{k}, A_{p} \in \mathcal{L}(\mathcal{E})\right\}= \\
& =\sup \left\{\left|\sum_{p \leq n} \sum_{k>n}\left\langle A_{k}^{*} \Gamma\left[f_{k}, f_{p}\right] A_{p} a, b\right\rangle\right| ; A_{k}, A_{p} \in \mathcal{L}(\mathcal{E})\right\}= \\
& =\sup \left\{\left|\sum_{p \leq n} \sum_{k>n}\left\langle A_{k}^{*} \Gamma\left[f_{k+m}, f_{p+m}\right] A_{p} a, b\right\rangle\right| ; A_{k}, A_{p} \in \mathcal{L}(\mathcal{E})\right\}= \\
& =\sup \left\{\left|\sum_{s \leq n+m} \sum_{j>n+m}\left\langle A_{j-m}^{*} \Gamma\left[f_{j}, f_{s}\right] A_{j-s} a, b\right\rangle\right| ; A_{k} \in \mathcal{L}(\mathcal{E})\right\}= \\
& =\sup \left\{\left|\sum_{s \leq n+m} \sum_{j>n+m}\left\langle B_{j}^{*} \Gamma\left[f_{j}, f_{s}\right] B_{s} a, b\right\rangle\right| ; B_{j}, B_{s} \in \mathcal{L}(\mathcal{E})\right\}= \\
& =\sup \left\{|\langle\Gamma[g, h] a, b\rangle| ; h \in \mathcal{H}_{n+m}^{f}, g \in \widetilde{\mathcal{H}}_{n+m}^{f}\right\}=\rho(n+m)
\end{aligned}
$$

for any $m \in \mathbb{Z}$.
In this paper only the one step ahead future is considered (2.7), but analogously the $p$-step ahead future can be constructed as

$$
\widetilde{\mathcal{H}}_{n, p}^{f}=\left\{\sum_{k} A_{k} f_{k} ; A_{k} \in \mathcal{L}(\mathcal{E}), k \geq n+p\right\},
$$

the corresponding subspace from the time domain $\mathcal{K}_{\infty}^{f} \subset \mathcal{K}$ being

$$
\widetilde{\mathcal{K}}_{n, p}^{f}=\bigvee_{j \geq n+p} V_{f_{j}} \mathcal{E}
$$

and the $p$-step prediction is done using informations from the past $\mathcal{H}_{n}^{f}$, obtained with the action of $\mathcal{L}(\mathcal{E})$ on $\left(f_{t}\right)$ from $\mathcal{H}$ till the moment $t=n$.

Similarly the angle $\rho(n, p)$ between the past $\mathcal{H}_{n}^{f}$ and the $p$-step ahead future $\widetilde{\mathcal{H}}_{n, p}^{f}$ can be considered and the fact that $\rho(n)<1$ is equivalent with $\rho(n, p)<1$ can be proved, giving the possibility to find the $p$-step ahead predictor.

Generalizing to stationary $\Gamma$-correlated case a result of [7] we have
Proposition 3.2. Let $\left(f_{n}\right)$ be a stationary $\Gamma$-correlated process in $\mathcal{H}$. The angle between past and future of $\left(f_{n}\right)$ is positive if and only if there exists a finite constant $C$ which depends only by $\left(f_{n}\right)$ such that for each element of the form $\sum V_{f_{n}} a_{n}$ from the time domain $\mathcal{K}_{\infty}^{f}$ and for each $-\infty \leq n_{1} \leq n_{2}<\infty$ we have

$$
\begin{equation*}
\left\|\sum_{k=n_{1}}^{n_{2}} V_{f_{k}} a_{k}\right\| \leq C\left\|\sum V_{f_{k}} a_{k}\right\|, \tag{3.3}
\end{equation*}
$$

where in the second term the sum has finitely many non-zero elements.
Proof. It is known [7] that for two subspaces $\mathcal{M}$ and $\mathcal{N}$ from a Hilbert space we have $\rho(\mathcal{M}, \mathcal{N})<1$ if and only if there exists a finite constant $C$ such that $\|x\| \leq C\|x+y\|$ for $x$ and $y$ generators in $\mathcal{M}$ and $\mathcal{N}$, respectively. Therefore for any sum of the form $\sum V_{f_{n}} a_{n}$ from the time domain $\mathcal{K}_{\infty}^{f}$, taking into account that $\rho\left(\mathcal{H}_{n}^{f}, \widetilde{\mathcal{H}}_{n}^{f}\right)<1$, we have

$$
\left\|\sum_{k \leq n} V_{f_{k}} a_{k}\right\| \leq C\left\|\sum_{k \leq n} V_{f_{k}} a_{k}+\sum_{k>n} V_{f_{k}} a_{k}\right\|=C\left\|\sum V_{f_{k}} a_{k}\right\|,
$$

where $\sum V_{f_{k}} a_{k}$ has finitely many non-zero elements. Since $\left(f_{n}\right)$ is stationary $\Gamma$-correlated, for any $m \in \mathbb{Z}$ we have

$$
\begin{gathered}
\left\|\sum_{k \leq m} V_{f_{k}} a_{k}\right\|_{\mathcal{K}}^{2}=\left\langle\sum_{k \leq m} V_{f_{k}} a_{k}, \sum_{p \leq m} V_{f_{p}} a_{p}\right\rangle=\sum_{k, p \leq m}\left\langle V_{f_{p}}^{*} V_{f_{k}} a_{k}, a_{p}\right\rangle_{\mathcal{E}}= \\
=\sum_{k, p \leq m}\left\langle\Gamma\left[f_{p}, f_{k}\right] a_{k}, a_{p}\right\rangle=\sum_{k, p \leq m}\left\langle\Gamma\left[f_{p-(m-n),}, f_{k-(m-n)}\right] a_{k}, a_{p}\right\rangle= \\
=\sum_{i, j \leq n}\left\langle\Gamma\left[f_{j}, f_{i}\right] a_{i}, a_{j}\right\rangle=\left\|\sum_{k \leq n} V_{f_{k}} a_{k}\right\|_{\mathcal{K}}^{2} \leq C^{2}\left\|\sum V_{f_{k}} a_{k}\right\|_{\mathcal{K}}^{2} .
\end{gathered}
$$

Therefore

$$
\begin{aligned}
& \quad\left\|\sum_{k=n_{1}}^{n_{2}} V_{f_{k}} a_{k}\right\|=\left\|\sum_{k \leq n_{2}} V_{f_{k}} a_{k}-\sum_{k<n_{1}} V_{f_{k}} a_{k}\right\| \leq \\
& \leq\left\|\sum_{k \leq n_{2}} V_{f_{k}} a_{k}\right\|+\left\|\sum_{k \leq n_{1}} V_{f_{k}} a_{k}\right\| \leq 2 C\left\|\sum V_{f_{k}} a_{k}\right\|
\end{aligned}
$$

and (3.3) is proved.
Also the property of representing the elements from the time domain of a process as a series (Schauder basis [10]) can be generalized for $\Gamma$-correlated processes.

Proposition 3.3. The angle between past and future of a stationary $\Gamma$-correlated process $\left(f_{n}\right)$ is positive if and only if each element $k$ from the time domain $\mathcal{K}_{\infty}^{f}$ can be uniquely represented in the form $k=\sum_{n=-\infty}^{\infty} k_{n}$ where $k_{n}$ are elements from $\overline{V_{f_{n}} \mathcal{E}}$.
Proof. Using the previous Proposition, if we take $Q_{n}\left(\sum V_{f_{k}} a_{k}\right)=V_{f_{n}} a_{n}$, then $\left(f_{n}\right)$ is of positive angle if and only if $Q_{n}$ is a linear operator on $\mathcal{K}_{\infty}^{f}$, for each $n \in \mathbb{Z}$, and $\sum_{n_{1}}^{n_{2}} Q_{i}$ are uniformly bounded operators and

$$
k=\lim _{n_{1}, n_{2}} \sum_{n_{1}}^{n_{2}} Q_{i} k=\sum_{-\infty}^{\infty} Q_{i} k=\sum_{-\infty}^{\infty} k_{n} .
$$

To prove the unicity, if $k=\sum_{-\infty}^{\infty} k_{n}^{\prime}$ with $k_{n}^{\prime} \in \overline{V_{f_{n}} \mathcal{E}}$, then by the fact that for $i \neq n$ we have $Q_{i} k=0$, and it follows that for $n \in \mathbb{Z}$

$$
k_{n}^{\prime}=Q_{n}\left(\sum_{n} k_{n}^{\prime}\right)=Q_{n} k=Q_{n}\left(\sum_{n} k_{n}\right)=k_{n} .
$$

Conversely, if each $k \in \mathcal{K}_{\infty}^{f}$ admits a unique representation of the form $k=\sum_{-\infty}^{\infty} k_{n}$ with $k_{n} \in \overline{V_{f_{n}} \mathcal{E}}$, then the operators $T_{n}: \mathcal{K}_{\infty}^{f} \rightarrow \overline{V_{f_{n}} \mathcal{E}}$ defined by $T_{n} k=k_{n}$ are well-defined, bounded and the family of elements of the form $\left\|\sum_{n=k}^{p} T_{n}\right\|$ is uniformly bounded, and by Proposition 3.2 it follows that the angle between past and future of $\left(f_{n}\right)$ is positive.

We have seen that each periodically $\Gamma$-correlated process $\left(f_{n}\right)_{n \in \mathbb{Z}}$ from $\mathcal{H}$ has a stationary $\Gamma_{1}$-correlated dilation $\left(X_{n}\right)$ in $\mathcal{H}^{T}$. In $[15]$ an explicit stationary dilation is constructed which help in obtaining the Wiener filter for prediction and the prediction-error operator function for a periodically $\Gamma$-correlated process, in terms of the operator coefficients of its attached
maximal function. Here we prove the following result concerning the angle of the stationary dilation of a periodically $\Gamma$-correlated process.

Proposition 3.4. If $\left(f_{n}\right)$ from $\mathcal{H}$ is a periodically $\Gamma$-correlated process with a positive angle between its past and future, then the angle between the past and the future of its stationary $\Gamma_{1}$-correlated dilation $\left(X_{n}\right)$ from $\mathcal{H}^{T}$ it is also positive.

Proof. Analogously as in (2.6) and (2.7), in $\mathcal{H}^{T}$ the past $H_{n}^{X}$ and the future $\tilde{H}_{n}^{X}$ for a process $\left(X_{n}\right) \subset \mathcal{H}^{T}$ is constructed as linear combinations of finite actions of $\mathcal{L}(\mathcal{E})$ on $\left(X_{n}\right) \subset \mathcal{H}^{T}$. If $\left(f_{n}\right)$ from $\mathcal{H}$ is a periodically $\Gamma$-correlated process having a positive angle between its past and future, then at each time $t=n$ there exists $\rho(n)<1$ such that

$$
\left|\langle\Gamma[g, h] a, b\rangle_{\mathcal{E}}\right| \leq \rho(n)\left\|V_{h} a\right\|\left\|V_{g} b\right\|
$$

for each $h \in \mathcal{H}_{n}^{f}$ and $g \in \tilde{\mathcal{H}}_{n}^{f}$. For each element $X=\sum_{k \leq n} A_{k} X_{k}$ from the past $H_{n}^{X}$ and $Y=\sum_{p>n} B_{p} X_{p}$ from the future $\tilde{H}_{n}^{X}$ of the $\Gamma_{1}$-correlated process $\left(X_{n}\right)$ given by (2.12), and for any $a, b \in \mathcal{E}$ we have

$$
\begin{gathered}
\left|\left\langle\Gamma_{1}[X, Y] a, b\right\rangle_{\mathcal{E}}\right|=\left|\left\langle\Gamma_{1}\left[\sum_{p>n} B_{p} X_{p}, \sum_{k \leq n} A_{k} X_{k}\right] a, b\right\rangle_{\mathcal{E}}\right|= \\
=\left|\sum_{p>n} \sum_{k \leq n}\left\langle\Gamma_{1}\left[B_{p} X_{p}, A_{k} X_{k}\right] a, b\right\rangle_{\mathcal{E}}\right|= \\
=\left|\sum_{p>n} \sum_{k \leq n} \sum_{i=0}^{T-1}\left\langle\Gamma\left[B_{p} f_{p+i}, A_{k} f_{k+i}\right] a, b\right\rangle_{\mathcal{E}}\right|= \\
=\left|\sum_{p>n} \sum_{k \leq n} \sum_{i=0}^{T-1}\left\langle B_{p}^{*} \Gamma\left[f_{p+i}, f_{k+i}\right] A_{k} a, b\right\rangle_{\mathcal{E}}\right|= \\
=\left|\sum_{i=0}^{T-1}\left\langle\Gamma\left[\sum_{p>n} B_{p} f_{p+i}, \sum_{k \leq n} A_{k} f_{k+i}\right] a, b\right\rangle\right| \leq \\
\leq \sum_{i=0}^{T-1} \rho_{i}(n)\left\|\sum_{k \leq n} A_{k} f_{k+i} a\right\|\left\|\sum_{p>n} B_{p} f_{p+i} b\right\| \leq \\
\leq \rho(n) \sum_{i=0}^{T-1}\left\|\sum_{k \leq n} A_{k} f_{k+i} a\right\|\left\|\sum_{p>n} B_{p} f_{p+i} b\right\| \leq \\
\leq \rho(n)\left(\sum_{i=0}^{T-1}\left\|\sum_{k \leq n} A_{k} f_{k+i} a\right\|\right)^{1 / 2}\left(\sum_{i=0}^{T-1}\left\|\sum_{p>n} B_{p} f_{p+i} b\right\|^{2}\right)^{1 / 2}= \\
=\rho\left\|\sum_{k \leq n} A_{k} W_{X_{k}} a\right\|\left\|\sum_{p>n} B_{p} W_{X_{p}} b\right\|=\rho\left\|W_{X} a\right\|\left\|W_{Y} b\right\|,
\end{gathered}
$$

where $\rho(n)$ is the maximum of $\rho_{i}(n)<1 ; i=0,1, \ldots, T-1$, and we used the embedding $X \rightarrow W_{X}$ of $\mathcal{H}^{T}$ into $\mathcal{L}\left(\mathcal{E}, \mathcal{K}^{T}\right)$ and the fact that $\rho(n)=\rho$ for stationary $\Gamma_{1}$-correlated proces $\left(X_{n}\right)$. Therefore $\left|\left\langle\Gamma_{1}[X, Y] a, b\right\rangle_{\mathcal{E}}\right| \leq \rho\left\|W_{X} a\right\|\left\|W_{Y} b\right\|$ for each $X \in H_{n}^{X}, Y \in \tilde{H}_{n}^{X}$,
and the angle between the past and the future of the stationary $\Gamma_{1}$-correlated dilation ( $X_{n}$ ) is positive.

A measure of the positive angle between the past and future is given by the operator $B \in \mathcal{L}(\mathcal{K})$ defined by [5]

$$
\begin{equation*}
B=P^{-} P^{+} P^{-} \tag{3.4}
\end{equation*}
$$

where $P^{-}$is the projection on the past and $P^{+}$is the projection on the future of a given process. More or less explicitly, in various situations this operator was used $[9,6,11,14,2]$.

Another angle between two subspaces $M_{1}$ and $M_{2}$ of a Hilbert space $\mathcal{K}$ is the Friedrichs angle [4] defined to be the angle in $[0, \pi / 2]$ whose cosine is given by

$$
\begin{equation*}
c\left(M_{1}, M_{2}\right):=\sup \left\{\left|\left\langle k_{1}, k_{2}\right\rangle\right| ; k_{i} \in M_{i} \cap M^{\perp} \cap B_{\mathcal{K}}, i \in\{1,2\}\right\}, \tag{3.5}
\end{equation*}
$$

where $M=M_{1} \cap M_{2}$ and $B_{\mathcal{K}}$ is the unit ball of $\mathcal{K}$.
$\mathrm{By}(3.2)$ and (3.5) it follows that $c\left(M_{1}, M_{2}\right) \leq \rho\left(M_{1}, M_{2}\right)$. Obviously we have $c\left(M_{1}, M_{2}\right)=$ $\rho\left(M_{1} \cap M^{\perp}, M_{2} \cap M^{\perp}\right)$, and of course $c\left(M_{1}, M_{2}\right)=c\left(M_{1}^{\perp}, M_{2}^{\perp}\right)$. Various properties of the angles between subspaces in a Hilbert space can be found in [2]. Here some properties of the Friedrichs angle and the generalized Friedrichs angle [1] are used in the case of periodically correlated processes in a complete correlated action $\{\mathcal{E}, \mathcal{H}, \Gamma\}$.

If we take $\left(X_{n}\right) \subset \mathcal{H}^{T}$ the stationary $\Gamma_{1}$-correlated dilation of a periodically $\Gamma$-correlated process $\left(f_{n}\right) \subset \mathcal{H}$, then the Friedrichs angle between the past and the future of $\left(X_{n}\right)$ is given by

$$
c\left(K_{n}^{X}, \tilde{K}_{n}^{X}\right)=\sup \left\{|\langle X, Y\rangle| ; X \in K_{n}^{X} \cap M^{\perp} \cap B_{1}, Y \in \tilde{K}_{n}^{X} \cap M^{\perp} \cap B_{1}\right\}
$$

where $M=K_{n}^{X} \cap \tilde{K}_{n}^{X}, B_{1}$ is the unit ball in $\mathcal{K}^{T}$, and $K_{n}^{X}$ and $\tilde{K}_{n}^{X}$ are the images of the past, respectively of the future from $\mathcal{K}^{T}$ by the embedding $X \rightarrow W_{X}$ of $\mathcal{H}^{T}$ into $\mathcal{L}\left(\mathcal{E}, \mathcal{K}^{T}\right)$

$$
\begin{equation*}
K_{n}^{X}=\bigvee_{k \leq n} W_{X_{k}} \mathcal{E}, \quad \tilde{K}_{n}^{X}=\bigvee_{j>n} W_{X_{j}} \mathcal{E} \tag{3.6}
\end{equation*}
$$

Even the angle between the past and the future of the stationary process $\left(X_{n}\right) \subset \mathcal{H}^{T}$ is constant, the angles between various pasts of the components of $X_{n}=\left(f_{n}, f_{n+1}, \ldots, f_{n+T-1}\right)$ are variable and can be characterized by the generalized Friedrichs angle between several subspaces. To do this, let us first remember the following characterization of the Friedrichs angle for two subspaces [1].

Proposition 3.5. If $M_{1}$ and $M_{2}$ are closed subspaces of $\mathcal{K}$, then the angle between $M_{1}$ and $M_{2}$ is given by

$$
\rho\left(M_{1}, M_{2}\right)=\sup \left\{\frac{2 \operatorname{Re}\left\langle m_{1}, m_{2}\right\rangle}{\left\|m_{1}\right\|^{2}+\left\|m_{2}\right\|^{2}} ; m_{j} \in M_{j},\left(m_{1}, m_{2}\right) \neq(0,0)\right\}
$$

and the Friedrichs angle is

$$
c\left(M_{1}, M_{2}\right)=\sup \left\{\frac{2 \operatorname{Re}\left\langle m_{1}, m_{2}\right\rangle}{\left\|m_{1}\right\|^{2}+\left\|m_{2}\right\|^{2}} ; m_{j} \in M_{j} \cap M^{\perp},\left(m_{1}, m_{2}\right) \neq(0,0)\right\}
$$

Then the Friedrichs angle to several subspaces $\left(M_{1}, M_{2}, \ldots, M_{T}\right)$ is defined [1] by

$$
\begin{equation*}
c\left(M_{1}, \ldots, M_{T}\right)=\sup \left\{\frac{2}{T-1} \frac{\sum_{j<k} R e\left\langle m_{j}, m_{k}\right\rangle}{\sum_{i=1}^{T}\left\|m_{i}\right\|^{2}}\right\} \tag{3.7}
\end{equation*}
$$

for $m_{j} \in M_{j} \cap M^{\perp}, \sum_{i=1}^{T}\left\|m_{i}\right\|^{2} \neq 0$.

In the case of a periodically $\Gamma$-correlated process $\left(f_{n}\right)$, since $M=\bigcap_{i=0}^{T-1} \mathcal{K}_{n+i}=\mathcal{K}_{n}^{f}$, we have the Friedrichs angle associated to $\left(\mathcal{K}_{n}^{f}, \mathcal{K}_{n+1}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}\right)$, corresponding to $X_{n}=$ $\left(f_{n}, f_{n+1}, \ldots, f_{n+T-1}\right)$, defined by its cosine (or Friedrichs number):

$$
\begin{equation*}
c\left(\mathcal{K}_{n}^{f}, \mathcal{K}_{n+1}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}\right)=\sup \left\{\frac{2}{T-1} \frac{\sum_{j<p} R e\left\langle k_{j}, k_{p}\right\rangle}{\sum_{i=0}^{T-1}\left\|k_{i}\right\|^{2}}\right\} \tag{3.8}
\end{equation*}
$$

for $k_{i} \in \mathcal{K}_{n+i}^{f} \cap\left(\mathcal{K}_{n}^{f}\right)^{\perp}, \sum_{i=0}^{T-1}\left\|k_{i}\right\|^{2} \neq 0$.
Analoguously, generalizing the angle $\rho$ between two subspaces to $T$ subspaces, a so called Dixmier number is obtained

$$
\begin{equation*}
\rho\left(\mathcal{K}_{n}^{f}, \mathcal{K}_{n+1}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}\right)=\sup \left\{\frac{2}{T-1} \frac{\sum_{j<p} R e\left\langle k_{j}, k_{p}\right\rangle}{\sum_{i=0}^{T-1}\left\|k_{i}\right\|^{2}}\right\} \tag{3.9}
\end{equation*}
$$

for $k_{i} \in \mathcal{K}_{n+i}^{f}, \quad \sum_{i=0}^{T-1}\left\|k_{i}\right\|^{2} \neq 0$.
Other definitions [1] of apparently geometric concepts which can help in the study of the geometry of some nonstationary processes are the following.

The configurant constant:

$$
\begin{equation*}
\kappa\left(\mathcal{K}_{n}^{f}, \mathcal{K}_{n+1}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}\right)=\sup \left\{\frac{1}{T} \frac{\left\|\sum_{j=0}^{T-1} k_{j}\right\|^{2}}{\sum_{i=0}^{T-1}\left\|k_{i}\right\|^{2}}\right\} \tag{3.10}
\end{equation*}
$$

for $k_{i} \in \mathcal{K}_{n+i}^{f} \cap\left(\mathcal{K}_{n}^{f}\right)^{\perp}, \sum_{i=0}^{T-1}\left\|k_{i}\right\|^{2} \neq 0$.
The non-reduced configurant constant:

$$
\begin{equation*}
\kappa_{0}\left(\mathcal{K}_{n}^{f}, \mathcal{K}_{n+1}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}\right)=\sup \left\{\frac{1}{T} \frac{\left\|\sum_{j=0}^{T-1} k_{j}\right\|^{2}}{\sum_{i=0}^{T-1}\left\|k_{i}\right\|^{2}}\right\} \tag{3.11}
\end{equation*}
$$

for $k_{i} \in \mathcal{K}_{n+i}^{f}, \quad \sum_{i=0}^{T-1}\left\|k_{i}\right\|^{2} \neq 0$.
The inclination of $\mathcal{K}_{n}^{f}, \mathcal{K}_{n+1}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}$ :

$$
\begin{equation*}
l\left(\mathcal{K}_{n}^{f}, \mathcal{K}_{n+1}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}\right)=\inf \left\{\frac{\max _{0 \leq j \leq T-1} \operatorname{dist}\left(k, \mathcal{K}_{n+j}^{f}\right)}{\operatorname{dist}\left(k, \mathcal{K}_{n}^{f}\right)}\right\} \tag{3.12}
\end{equation*}
$$

for $k \notin \mathcal{K}_{n}^{f}$.
Proposition 3.6. For a periodically $\Gamma$-correlated process $\left(f_{n}\right)_{n \in \mathbb{Z}}$ from $\mathcal{H}$, the configuration constant $\kappa$ of the past spaces associated to its stationary $\Gamma_{1}$-correlated dilation $\left(X_{n}\right)$ from $\mathcal{H}^{T}$ is given by

$$
\begin{equation*}
\kappa\left(\mathcal{K}_{n}^{f}, \mathcal{K}_{n+1}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}\right)=\sup \left\{\frac{1}{T}\left\|G\left(k_{0}, \ldots, k_{T-1}\right)\right\|\right\} \tag{3.13}
\end{equation*}
$$

for $k_{j} \in \mathcal{K}_{n+j} \cap\left(\mathcal{K}_{n}^{f}\right)^{\perp},\left\|k_{j}\right\|=1, j=0,1, \ldots, T-1$, where the matrix $G$ is given by

$$
G\left(k_{0}, \ldots, k_{T-1}\right)=\left(\left\langle k_{i}, k_{j}\right\rangle_{\mathcal{K}}\right)_{i, j=0}^{T-1}
$$

and

$$
\begin{equation*}
\left\langle k_{i}, k_{j}\right\rangle_{\mathcal{K}}=\left\langle\Gamma_{T}\left[Y_{i}, Y_{j}\right] \boldsymbol{b}, \boldsymbol{c}\right\rangle_{\mathcal{E}^{T}}, \tag{3.14}
\end{equation*}
$$

$Y_{i}=\left(0, f_{n+1}, \ldots, f_{n+i}, 0, \ldots, 0\right) \subset \mathcal{H}^{T}$, while $\boldsymbol{b}$ and $\boldsymbol{c}$ are vectors from $\mathcal{E}^{T}$.

Proof. The characterization (3.13) of the configurant constant $\kappa$ it follows by Proposition3.4 from [1], taking into account that $\bigcap_{i} \mathcal{K}_{n+i}^{f}=\mathcal{K}_{n}^{f}$. To prove (3.14), let us consider the generators $k_{j}$ from $\mathcal{K}_{n+j} \cap\left(\mathcal{K}_{n}^{f}\right)^{\perp}, k_{j}=\sum_{k=0}^{j} \sum_{r} A_{r} V_{f_{n+k}} a_{r}, j=0,1, \ldots, T-1$, where $A_{r} \in$ $\mathcal{L}(\mathcal{E}), a_{r} \in \mathcal{E}$, and the sums $\sum_{r}$ have finite non-zero terms. Then, taking into account the action of $\mathcal{L}(\mathcal{E})$ on $\mathcal{H}$ and the definition (2.11) of the $\Gamma_{T}$-correlation on $\mathcal{H}^{T}$, we have

$$
\begin{gathered}
\left\langle k_{i}, k_{j}\right\rangle_{\mathcal{K}}=\left\langle\sum_{k=0}^{i} \sum_{r} A_{r} V_{f_{n+k}} a_{r}, \sum_{p=0}^{j} \sum_{s} A_{s} V_{f_{n+p}} a_{s}\right\rangle= \\
=\left\langle\sum_{k=0}^{i} \sum_{r} V_{f_{n+k}} A_{r} a_{r}, \sum_{p=0}^{j} \sum_{s} V_{f_{n+p}} A_{s} a_{s}\right\rangle= \\
=\sum_{k=0}^{i} \sum_{p=0}^{j}\left\langle V_{f_{n+p}}^{*} V_{f_{n+k}} \sum_{r} A_{r} a_{r}, \sum_{s} A_{s} a_{s}\right\rangle= \\
=\sum_{k=0}^{i} \sum_{p=0}^{j}\left\langle\Gamma\left[f_{n+p}, f_{n+k}\right] b_{k}, c_{p}\right\rangle= \\
=\sum_{k=0}^{T} \sum_{p=0}^{T}\left\langle\Gamma\left[f_{n+p}, f_{n+k}\right] b_{k}, c_{p}\right\rangle=\left\langle\Gamma_{T}\left[Y_{p}, Y_{k}\right] \mathbf{b}, \mathbf{c}\right\rangle_{\mathcal{E}^{T}}
\end{gathered}
$$

Considering $\mathbf{C}$ the cartesian product of $\mathcal{K}_{n}^{f}, \mathcal{K}_{n+1}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}$ and $\mathbf{D}$ the diagonal of $\mathcal{K}^{T}, \mathbf{D}=\{(k, \ldots, k) ; k \in \mathcal{K}\}$, in a similar way as in [1] can be proved the following characterization of the configurant constant and of the inclination of the past subspaces $\mathcal{K}_{n}^{f}, \mathcal{K}_{n+1}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}$ associated to the $\Gamma_{1}$-correlated dilation $\left(X_{n}\right)$ of a periodically $\Gamma$ correlated process $\left(f_{n}\right)$.

Proposition 3.7. For $T \geq 2$ we have
(i) $\rho\left(\mathcal{K}_{n}^{f}, \mathcal{K}_{n+1}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}\right)=\rho(\boldsymbol{C}, \boldsymbol{D})^{2}$,
(ii) $c\left(\mathcal{K}_{n}^{f}, \mathcal{K}_{n+1}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}\right)=c(\boldsymbol{C}, \boldsymbol{D})^{2}$,
(iii) $1-l\left(\mathcal{K}_{n}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}\right) \leq c(\boldsymbol{C}, \boldsymbol{D}) \leq 1-\frac{1}{2 T} l\left(\mathcal{K}_{n}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}\right)^{2}$.

Thus the inclination of the sequence of attached pasts subspaces $\mathcal{K}_{n}^{f}, \mathcal{K}_{n+1}^{f}, \ldots, \mathcal{K}_{n+T-1}^{f}$ is zero if and only if its Friedrichs angle is 1.

As previously was mentioned, in this paper the case $G=\mathbb{Z}$ was considered, but nice specific geometrical aspects arise in various other cases. So, in the case when $G$ is $\mathbb{Z}^{2}=\mathbb{Z} \times \mathbb{Z}$, the double sequence $\left(f_{m, n}\right)_{(m, n) \in \mathbb{Z}^{2}}$ from $\mathcal{H}$ is a $\Gamma$-correlated process, with an appropriate correlation, which is stationary if $\Gamma\left[f_{m, n}, f_{r, s}\right]$ depends only on the differences $m-r$ and $n-s$. Here a lot of geometrical aspects arise if we consider the vertical (horizontal) pasts and futures and also the vertical (horizontal) angles between various pasts and futures of the process. The geometry becomes more interesting in the case of the periodicity of the process $\left(f_{m, n}\right)$ considering the period $T=\left(T_{1}, T_{2}\right)$, but this will be done into another paper, requiring a separately specific study.

## References

[1] C. Badea, S. Grivaux, V. Muller, The rate of convergence in the method of alternating projections. Algebra i Analiz 23, 3(2011), 1-30; translation in St. Petersburg Math. J. 23, 3(2012), 413-434.
[2] F. Deutsch, The angle between subspaces of a Hilbert space. Approximation theory, wavelets and applications (Maratea, 1994), 107-130, NATO Adv. Sci. Inst. Ser. C Math. Phys. Sci., 454, Kluwer Acad. Publ., Dordrecht, 1995.
[3] J. Dixmier, Étude sur les variétés et les opérateurs de Julia avec quelques applications. Bull. Soc. Math. France, 77(1949), 11-101.
[4] K. Friedrichs, On certain inequalities and characteristic value problems for analytic functions and for functions of two variables. Trans. Amer. Math. Sooc. 41(1937), 321-364.
[5] I. M. Gelfand and A. M. Yaglom, Calculation of the amount of information about a random function contained in another such function. (Russian), Uspekhi Math. Nauk, 12(1957), 3-52.
[6] I. Halperin, The product of projection operators. Acta Sci. Math. (Szeged) 23(1962), 96-99.
[7] H. Helson and G. Szegő, A problem in prediction theory. Ann. Mat. Pura. Appl. 51 (1960), 107-138.
[8] H. Helson and D. Sarason, Past and future. Math. Scand. 21(1967), 5-16.
[9] I. A. Ibrahimov and Y. A. Rozanov, Gaussian random processes. Springer Verlag, 1978.
[10] A.G. Miamee and H. Niemi, On the angle for stationary random fields. Ann. Acad. Sci. Fenn. 17(1992), 93-103.
[11] I. Suciu, Operatorial extrapolation and prediction. Operator Theory: Advances and Applications, Birkha̋user Verlag, Basel, 28(1988), 291-300.
[12] I. Suciu and I. Valusescu, Factorization theorems and prediction theory. Rev. Roumaine Math. Pures et Appl. 23, $9(1978)$, 1393-1423.
[13] I. Suciu, and I. Valusescu, A linear filtering problem in complete correlated actions. Journal of Multivariate Analysis, 9, 4(1979), 559-613.
[14] D. Timotin, Prediction theory and choice sequences: an alternate approach. Advances in invariant subspaces and other results of operator theory, Birkha̋user Verlag, Basel, 1986, 341-352.
[15] I. Valusescu, A linear filter for the operatorial prediction of a periodically correlated process. Rev. Roumaine Math. Pures et Appl. 54, 1 (2009), 53-67.

$$
\text { Received } 8 \text { November } 2013
$$

Institute of Mathematics "Simion Stoilow" of the Romanian Academy, Calea Griviţei nr. 21, Bucharest, Romania. Research unit nr. 1

E-mail address: ilie.valusescu@imar.ro


[^0]:    2000 Mathematics Subject Classification. 47N30, 47A20, 60G25.
    Key words and phrases. Complete correlated actions, $\Gamma$-correlated processes, projection, stationary dilation, angle between past and future, Friedrichs angle, periodically $\Gamma$-correlated processes.

    Supported by UEFISCDI Grant PN-II-ID-PCE-2011-3-0119.

