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INTRODUCTION. The aim of this paper is to construct an iterative multigrid process for variational nonsymmetric problems defined by continuous, elliptic type, nonsymmetric bilinear functionals, such that the bounds obtained for the rate of convergence be independent of the approximation subspacesive. of discretization parameters - and depending only of the continuity and ellipticity constants. Using an natural framework for the discrete problems such that the Nicolaides variational relations (1.5 and 1.17) are fullfiled and using a Hackbusch type decomposition for the two-grid iteration operator, constructed with an adequate relaxation process, we obtain bounds of same type as in multigrid literature.

- \$1. Approximation on subspaces. Let H be a real separable Hilbert space with <.,. inner product and II. II the coresponding norm. We consider on H the following problem:
- (P) Given f a bounded linear functional on H, find $u \in H$ such that $\partial_u(u,v)=f(v)$ for every $v \in H$,

where a is a nonsymmetric, bilinear functional on \mathbb{H} , that satisfies the following properties: there exist the constants \propto and \mathbb{B} such that:

(1.1) |a(w,v)| {B ||w|| . ||v||

(1.2) |a(w, w)|7 4 || w || 2

for every w, ve H.

By the well knowed Lax-Milgram lemma, this problem has a unique solution uel. Now, let A be the linear operator on H, bounded and nonsingular, defined by Riesz representation, unique determined by:

$$(1.3) \quad a(w,v) = \langle Rw, v \rangle$$

for every w, ve H.

If μ_k is an finite dimension subspace of μ , then by P_k we denote the orthogonal projection operator corresponding it. The restriction of the bilinear functional a at H_k defines on \mathcal{H}_k an linear operator \mathcal{A}_k by

$$a(w_k, v_k) = \langle A P_k w_k, P_k v_k \rangle = \langle (P_k A P_k) w_k, v_k \rangle$$

for every wk, vke Wk, hence

$$(1.4) \quad A_k = P_k A P_k$$

As linear operator on \mathcal{H}_k , \mathcal{A}_k is bounded and nonsingular because (1.1) and (1.2) hold on \mathcal{H}_{k} .

Let \mathbb{R}_k be the finite dimension real space, $\dim \mathbb{R}_k$ = $\dim \mathcal{H}_k$ = = n_k , equipped with the Euclidean inner product $\langle \cdot, \cdot \rangle_k$ the corresponding norm $\|\cdot\|_{k}$. If $J_k:\mathcal{H}_k\to\mathbb{R}_k$ is an bijection operator, then we define Jk:Rk-7 Hk by

(1.5) $J_{k}^{k}J_{k}^{*}$, i.e, (1.5) $\langle J_{k}w_{k}, \overline{v}_{k} \rangle_{k} = \langle w_{k}, J^{k}\overline{v}_{k} \rangle$, for every $w_{k} \in \mathcal{H}_{k}, \overline{v}_{k} \in \mathcal{R}_{k}$.

On R_k we define now, the linear operator corresponding to A_k by

notting that for every wk, vkerk:

$$(1.7) \langle A_{k} \overline{w}_{k}, \overline{v}_{k} \rangle_{k} = \langle A_{k} (J^{k} \overline{w}_{k}), J^{k} \overline{v}_{k} \rangle_{\bullet}$$

With this, we can construct the discrete problems corresponding to \mathbb{H}_k and \mathbb{R}_k subspaces, of the problem (?).

Let $f^* \in \mathbb{H}$ be the Riesz representation of the bounded linear functional f:

(1.8) $f(v) = \langle f^{*}, v \rangle$, for every veh,

and let f_k^* be the projection of f^* : $f_k^*=P_kf^*$, on \aleph_k .

The discrete problem on \aleph_k , corresponding of the problem (P) is:

 $(P_k) \qquad \text{To find } u_k \mathcal{H}_k \text{ such that} \\ \partial (u_k, v_k) = f(v_k) \text{ for every } v_k \mathcal{H}_k \ ,$

and the two following problems are equivalent with $({}^{9}_{\mathbf{k}})$:

(P'_k) To find $u_k \in \mathcal{H}_k$ such that $\langle \mathcal{A}_k u_k, v_k \rangle = \langle f^*, v_k \rangle$ for every $v_k \in \mathcal{H}_k$, (1.9) $\langle \mathcal{A}_k u_k, v_k \rangle = \langle f_k^*, v_k \rangle$ for every $v_k \in \mathcal{H}_k$.

On R_k we define the discrete problem corresponding at \mathcal{P}_k :

(1.10) Given $\bar{f}_k^* \in \mathbb{R}_k$, to find $\bar{u}_k \in \mathbb{R}_k$ such that $A_k \bar{u}_k = \bar{f}_k^*$, where $\bar{f}_k^* = J_k f_k^*$

l.l. Remark: If $\bar{u}_k \in R_k$ is solution of (1.10) then $J^k \bar{u}_k$ is solution of (P_k) .

 $\underline{\text{Proof}}_{\bullet}$. For every $\overline{v}_k \epsilon R_k$, we have the following equivalent relations:

$$\begin{split} &\langle \mathbf{A}_k \bar{\mathbf{u}}_k - \bar{\mathbf{f}}_k^*, \bar{\mathbf{v}}_k \rangle_k = 0 \\ &\langle \mathbf{J}_k \mathbf{R}_k \mathbf{J}^k \bar{\mathbf{u}}_k, \bar{\mathbf{v}}_k \rangle_k = \langle \bar{\mathbf{f}}_k^*, \; \bar{\mathbf{v}}_k \rangle_k \;, \; \text{in } \mathbf{R}_k, \; \text{and} \\ &\langle \mathbf{A}_k (\mathbf{J}^k \bar{\mathbf{u}}_k), \mathbf{J}^k \bar{\mathbf{v}}_k \rangle = \langle \mathbf{f}_k^* \mathbf{J}^k \mathbf{v}_k \; \rangle \;, \; \text{in } \mathbf{H}_k. \end{split}$$

Because J^k is an bijection operator, the last relation is equivalent with $(\mathcal{P}_k^*)_*$

Let the following increasing sequence of finite dimension approximation subspaces of \mathcal{H} :

By the level or grid k, we understand one or both of the subspaces \mathbb{H}_k and \mathbb{R}_k and we point out this dependence by the dependence of the k. For the ulterior estimations we need the following equivalence relations of the \mathbb{H}_k and \mathbb{R}_k - norms:

$$(1.11) \qquad c_{1} \|J^{k} \bar{v}_{k}\| \leq c_{k} \|\bar{v}_{k}\|_{k} \leq c_{2} \|J^{k} \bar{v}_{k}\|,$$

for every $\bar{v}_k^{\,\varepsilon} R_k$, where c_1, c_2 not depend of k.

1.2. Remark. Choosing convenable the linear operator J^k we obtain a such equivalence relation as (1.11). For example, let $\{e_k^j|j=1,n_k\}$ be the natural basis of R_k and $\mathbb{I}_k=\mathrm{span}\,\{\phi_k^j|j=1,n_k\}$, where the above family is orthonormal in \mathbb{I}_k . Then, defining J^k by: $J^k e_k^j = \phi_k^j$, $j=1,n_k$, we obtain (1.11), by $\|\bar{\mathbf{v}}_k\|_k = \|J^k \bar{\mathbf{v}}_k\|$, for every $\bar{\mathbf{v}}_k \in R_k$. Hence, always holds an relation of the type (1.11), proved by this particular form.

1.1. Lemma. If (1.11) holds, then

(1.12)
$$\|A_k\|_{s} \le \frac{c_1^2 t_2^2}{c_1^2}$$

(1.13) $\|A_k^{-1}\|_s \le \frac{C_2^2}{\alpha} t^{-2}$; where $\|\cdot\|_s$ -denotes the spectral norm.

<u>Proof.</u> Because for every $\bar{w}_k, \bar{v}_k \in R_k$ we have (1.4), (1.5), (1.6),

$$a(J^{k}\bar{\mathbf{v}}_{k},J^{k}\bar{\mathbf{w}}_{k}) = \langle \mathbf{A}_{k}\bar{\mathbf{v}}_{k}, \bar{\mathbf{w}}_{k} \rangle_{k},$$

we obtain for the first estimation:

For the second estimation we observe that:

$$\frac{d \frac{\chi_{k}^{2}}{G_{2}^{2}} \|A_{k}^{-1} \bar{v}_{k}\|_{k}^{2} \langle \alpha \|J^{k} A_{k}^{-1} \bar{v}_{k}\|_{2}^{2} \langle |\alpha (J^{k} A_{k}^{-1} \bar{v}_{k}, J^{k} A_{k}^{-1} \bar{v}_{k})|}{\langle |\langle \bar{v}_{k}, A_{k}^{-1} \bar{v}_{k} \rangle_{k} |\langle || \bar{v}_{k} ||_{k}^{2} \|A_{k}^{-1} \bar{v}_{k} ||_{k}^{2}}$$

This estimations proves (1.12) and (1.13).

Now, for every kal we define the diagram (∂_k) :

where: P_k, P_{k-1} are the projections operators on \mathbb{H}_k and \mathbb{H}_{k-1} ; J_{k-1} are bijection operators and J_k is the transpose of

an injection operator $I_{k-1}^k: R_{k-1} \to R_k$, i.e.:

$$(1.15) \langle I_k^{k-1} \overline{v}_k, \overline{v}_{k-1} \rangle_{k-1} = \langle \overline{v}_k, I_{k-1}^k \overline{v}_{k-1} \rangle_k,$$

for every $\bar{v}_k^{\in R_k}$, $\bar{w}_{k-1}^{\in R_{k-1}}$. By "id" we denote the identity on $\mathcal H$.

l.l. Theorem . If the diagram (\mathcal{D}_k) is commutative, and (1.11) holds, then:

(1.16)
$$J_{k-1}P_{k-1} = I_k^{k-1}J_kP_k$$

$$(1.17) \quad A_{k-1} = I_{k}^{k-1} A_{k} I_{k-1}^{k}$$

$$(1.18) \quad \|\mathbf{I}_{k-1}^{k}\mathbf{D}_{k-1}\mathbf{I}_{k}^{k-1}\|_{s} \leqslant c_{3} \left(\frac{\delta_{k-1}}{\delta_{k}}\right)^{2} \cdot \|\mathbf{D}_{k-1}\|_{s}; \quad c_{3} = c_{2}^{2}/c_{1}^{2}$$

for every linear operator Dk-1 on Rk-1.

Proof: The first relation is equivalent with the comutativity of the diagram. Using (1.4), (1.6), (1.16), we obtain:

$$\begin{split} \mathbf{A}_{k-1} &= \mathbf{I}_{k-1} \mathbf{A}_{k-1} \mathbf{J}^{k-1} = \mathbf{J}_{k-1} \mathbf{P}_{k-1} \mathbf{A} \, \mathbf{P}_{k-1} \mathbf{J}^{k-1} = \mathbf{I}_{k}^{k-1} \mathbf{J}_{k} \mathbf{P}_{k} \mathbf{A} \, \mathbf{P}_{k} \mathbf{J}^{k} \mathbf{I}_{k-1}^{k} = \\ &= \mathbf{I}_{k}^{k-1} \mathbf{A}_{k} \mathbf{I}_{k-1}^{k} \, . \end{split}$$

Now, by (1.11), we have:

Particularly, we obtain by the theorme 1.1, that

$$\|\mathbf{I}_{k-1}^{k}\mathbf{I}_{k}^{k-1}\|_{s} c_{3}(\frac{r_{k-1}}{r_{k}})^{2}.$$

1.3. Remark: If we restrict the diagram $({}^9_k)$ at 9_k , then the commutativity is equivalent with:

$$(1.16^{\circ})$$
 $J_{k-1}^{P_{k-1}} = I_{k}^{k-1} J_{k}$

and this relation holds iff holds

(1.16")
$$P_{k-1}J^{k-1}=J^kI_{k-1}^k$$

For to prove the equivalence relation (1.16°) with (1.16"), let $\bar{\mathbf{v}}_{k-1} \in \mathbf{R}_{k-1}$, firstly; then for every $\mathbf{u}_k \in \mathcal{H}_k$, by (1.5°), (1.15), (1.16°):

$$\langle P_{k-1} J^{k-1} \bar{v}_{k-1}, u_k \rangle = \langle \bar{v}_{k-1}, J_{k-1} P_{k-1} u_k \rangle_{k-1} = \langle \bar{v}_{k-1}, I_k^{k-1} J_k u_k \rangle_{k-1}$$

$$= \langle J^k I_{k-1}^k \bar{v}_{k-1}, u_k \rangle$$

what proves that (1.16°) implies (1.16"). Converselly, let $u_k \in \mathbb{R}_k$; then for every $\bar{v}_{k-1} \in \mathbb{R}_{k-1}$, we have:

$$\langle J_{k-1}P_{k-1}u_k, \bar{v}_{k-1} \rangle_{k-1} = \langle u_k, P_{k-1}J^{k-1}\bar{v}_{k-1} \rangle = \langle u_k, J^kI_{k-1}^k\bar{v}_{k-1} \rangle$$

$$= \langle I_k^{k-1}J_ku_k, \bar{v}_{k-1} \rangle_{k-1}$$

1.4. Remark. The Galerkin method conducts to a commutative diagram.

Proof. Let $\mathcal{H}_{\ell} = \operatorname{span}\{\phi_{\ell}^{j} \ j=1,n_{\ell}\}$, $\ell=k-1;k$, where both families are linear independent in \mathcal{H} . Because $\mathcal{H}_{k-1} = \mathcal{H}_{k}$, there exists the matrix $T=[t_{ij}]$, i=1, n_{k-1} ; $j=1,n_{k}$, unique determined by

 $\begin{array}{l} \varphi \stackrel{i}{k-1} = \stackrel{\Gamma}{\sum} t_{ij} \varphi_k^j \text{ Now, the "stifness" Galerkin matrix \tilde{A}_{k-1}, \tilde{A}_k are defined by the entries $a_{ij}^\ell = \langle l \varphi_\ell^j, \varphi_\ell^i \rangle$, $i,j=l,n_\ell$, $\ell=k-1$, k. We define <math display="block"> \stackrel{k}{\text{Tk-1}} \stackrel{*}{\approx} R_{k-1} \rightarrow R_k$, by $\Gamma_{k-1}^k = \stackrel{n_k}{\sum} t_{ij} e_k^j$; \\ J^\ell: R_\ell \rightarrow \mathcal{H}_\ell$, by $J^\ell e_\ell^i = \varphi_\ell^i$, $i=l,n_\ell$; $\ell=k-1$, k. \end{array}$

Then, is a simple verification that for every $\bar{v}_{k-1} \in R_{k-1}$, we have $J^{k-1}\bar{v}_{k-1} = J^{k}I^{k}_{k-1}$, what proves that (1:16") is verified, and, by 1.3. Remark, the diagram (\mathfrak{I}_{k}) is commutative. Moreover, between the Galerkin matrix there exist the following relation $\bar{A}_{k-1} = T\bar{A}_{k}T^{*}$.

- §2. Two-grid convergence. For to solve numerically the equation (1.10) by multigrid method, such that the bound of the rate of convergence be independent of approximation subspaces, we suppose that are satisfied the following properties, for kil:
 - I) the diagram (1.14) is commutative
- II) the norms equivalence relation (1.11) holds, where c_1 and c_2 are independent of k.

Let k be fixed by stationary iterative process for the equation (1.10) we understand the iterations sequence:

(2.1)
$$\bar{u}_k^{j+i}=G_k$$
 $\bar{u}_k^{j}+D_k\bar{f}_k^{\star}$; $j=1,2,\ldots$, where

$$(2.2) \quad G_{k} = I_{k} - D_{k} A_{k};$$

 I_k is the indentity on R_k , and D_k is an linear operator on R_k . The spectral radius of the iteration operator G_k , $\xi(G_k)$ gives the rate of convergence if $\xi(G_k) < 1$. If D_k is constructed only by help of the k level, then we name a such process as relaxation process on k level.

The two-grid iterative process is defined as follows:

in the (j+1) step we determine the (j+1) iteration \bar{u}_k^{j+1} by: i) \Im -sweeps of relaxation on k level are efectuated:

$$\bar{u}_{k}^{\hat{j},\hat{i}+4} = G_{k}\bar{u}_{k}^{\hat{j},\hat{i}} + D_{k}\bar{f}_{k}^{*}, k=0,..., \vartheta-1; \bar{u}_{k}^{\hat{j},c} = \bar{u}_{k}^{\hat{j}};$$

Let $\bar{u}_k^{j,\delta}$ be after relaxation;

- ii) The k-level defect, $\bar{d}_k=\bar{f}_k^k-A_k\bar{u}_k^j$, is representated on coarse level k-l: $\bar{d}_{k-1}=I_k^{k-1}\bar{d}_k$
- iii) Exact solution on k-1 level is efectuated: $A_{k-1} \overline{v}_{k-1} = \overline{d}_{k-1}$ iv) the coarse correction $\overline{v}_k = I_{k-1}^{\kappa} \overline{v}_{k-1}$ is added at j-iteration for to obtain the (j+4)-iteration:

The two-grid iterative process defines an iterative stationary process on $\mathbf{R}_{\mathbf{k}}$ with the iteration operator $\mathbf{M}_{\mathbf{k}}$:

(23)
$$M_k = (I_k - B_k A_k) G_k$$
, where

(24)
$$B_{k} = I_{k-1}^{k} A_{k-1}^{k-1} I_{k}^{k-1}$$

and we use the following decomposition ([3]) of it:

(2.5)
$$M_{k} = (A_{k}^{-1} - B_{k}) (A_{k}G_{k}^{3}).$$

2.1. Lemma. In the hypothesis I)- II), we have the following estimations for every kyl:

(2.6)
$$\|A_k^{-1} - B_k\|_{8} < c_5 t_k^{-2}, \quad c_5 = \frac{c_8^2}{8} (1 + c_3)$$

(2.7)
$$\|A_k G_k^{\gamma}\|_{S} \leq \frac{1}{\omega_k} g(\gamma)$$

where the relaxation operator Gk has the form:

(2.8)
$$G_k = I_k - \omega_k^2 A_k^* A_k$$
, $\omega_k = 1/\|A_k\|_8$

and g is a monotone decreasing function of ?:

(2.9)
$$g(9) = \frac{1}{2}\sqrt{3/(49+1)}$$
.

Proof: From (1.13), (1.18), we obtain:

$$\|A_{k}^{-1} - B_{k}\|_{s} \leq \|A_{k}^{-1}\|_{s} + \|I_{k-1}^{k} A_{k-1}^{-1} I_{k}^{k+1}\|_{s} \leq \|A_{k}^{-1}\|_{s} + C_{3} \|A_{k}^{-1}\|_{s} \left(\frac{t_{K-1}}{t_{k}}\right)^{2}$$

$$\leq (C_{3} + 4) \frac{c_{2}^{2}}{c_{1}^{2}} \sqrt{k^{2}}$$

Now, for the second estimation, we observe that $\mathbb{A}_k^{\sharp}\mathbb{A}_k$ being an symmetric, positive linear operator, his eigenvalues $\{\lambda_j; j=1,m\}$ are positives. Then,

$$\begin{split} \| \mathbf{A}_{k} \mathbf{G}_{k}^{2} \|_{s}^{2} &= \| \mathbf{A}_{k} \mathbf{G}_{k}^{2} \mathbf{A}_{k}^{\pm} \|_{s} = g(\mathbf{A}_{k} \mathbf{G}_{k}^{2} \mathbf{A}_{k}^{\pm}) = g(\mathbf{A}_{k}^{\pm} \mathbf{A}_{k} \mathbf{G}_{k}^{2}) = \\ &= g(\mathbf{A}_{k}^{\pm} \mathbf{A}_{k} (\mathbf{I}_{k} - \omega_{k}^{2} \mathbf{A}_{k}^{\pm} \mathbf{A}_{k})^{2}) = \max \left[\lambda_{j} (1 - \omega_{k}^{2} \lambda_{j})^{2} \right] \\ &= \left[\lambda_{j} (1 - \omega_{k}^{2} \lambda_{j})^{2} \right] \\ &\leq \frac{1}{\omega_{k}^{2}} \sup_{0 \in X \in \mathbb{I}} \left[X(1 - X)^{2} \right] \end{split}$$

because $\lambda_j \omega_k^2 \langle \lambda_{\text{max}} / \| A_k \|_S^2 \leq 1$. In [3] is given the following estimation: sup $[X(1-X)^S] \leq 3/[8(s+1/2)]$. Hence, with g of the form (2.13) we obtain (2.7).

Hackbusch ([3]) names the relations (2.6) and (2.7) the approximation and smoothing properties.

2.2. Theorem of convergence. If the approximation and smoothing properties (2.6) and (2.7) holds, then in the hypothesis I), II), for every $\xi \in (0,1)$ there exists θ_0 depending only θ_0 such that

(2.10)
$$\| M_{k} \| \leq C_{5} g(v) \leq \frac{3}{5} < 1$$
, $C_{6} = C_{5} \frac{\rho}{C_{1}^{2}}$.

Proof: From (2.6) and (2.7) we have:

$$\|\mathbf{M}_{k}\|_{s} \leq \|\mathbf{A}_{k}^{-1} - \mathbf{B}_{k}\|_{s} \|\mathbf{A}_{k} \mathbf{G}_{k}\|_{s} \leq c_{5} \zeta_{k}^{-2} \cdot \frac{1}{\omega_{k}} g(\mathbf{F})$$

Because by (1.12) $1/\omega_k < \frac{C}{C_1^2} \sqrt[4]{2}$, we obtain the first inequality in (2.10). Now, let $\sqrt[3]{2}$ the smalest $\sqrt[3]{2}$ such that $C_6g(\sqrt[3]{2}) < \sqrt[3]{2}$, where $\sqrt[3]{2}$ is fixed in (0.1) interval. This $\sqrt[3]{2}$, there exists by the decreasing monotony of g. Hence

$$g(M_k) \leq \|M_k\|_{s} \leq \frac{5}{4}$$

for every $\sqrt{3}$, i.e. the two-grid iterative process converges, and the bound for the rate of convergence is independent of the level k.

§3. <u>Multigrid convergence</u>. If in the step iii) of the two-grid algorithm instead of exact solver we use an two-grid algorithm (k-1, k-2), we obtain an three-grid algorithm, and so on. Let 1,72 be fixed. The multigrid iterative process corresponding at the levels Hockline is caracterized by the following recursion ([10]):

where 671 is the number of the multigrid iterations on intermediary grid k, same for every k71. Let M_{k+1}^k be the two-grid iteration operator corresponding at levels (k+1,k) as in second paragraph. Then,

(3.2)
$$M_{k+1} = M_{k+1}^k + \Gamma_k^{k+1} M_{k}^k A_k^{k-1} \Gamma_{k+1}^k A_{k+1}^{k} G_{k+1}^{k}$$
, k21

- 3.1. Remark. In the I), II) hypothesis, we obtain the following estimation for the norm of multigrid iteration operator:
- (3.3) $\|\mathbf{M}_{k+1}\|_{s} = \frac{c_{\gamma} + \delta_{\gamma}}{\|\mathbf{M}_{k}\|_{s}}, \text{ where}$ $c_{\gamma} = \frac{c_{6}s(\gamma)}{\|\mathbf{M}_{k+1}\|_{s}}, \text{ by (2.10)}$
- (3.4) $\delta_{\gamma} = c_{7}g(\gamma)$, with $c_{7} = c_{3}c_{1}^{2}c_{2}^{2}/\alpha\rho$.

Indeed, $\|\mathbf{I}_{k}^{k+1}\mathbf{D}_{k}\mathbf{I}_{k+1}^{k}\|_{s} \leq c_{3} (\frac{\varepsilon_{k}}{\varepsilon_{k+1}})^{2} \|\mathbf{D}_{k}\|_{s}$, $\mathbf{D}_{k} = \mathbf{M}_{k} \mathbf{A}_{k}^{-1}$ by commutativity of the diagram \mathcal{J}_{k+1} , and by (2.6) and (2.7), $\|\mathbf{I}_{k}^{k+1}\mathbf{D}_{k}\mathbf{I}_{k+1}^{k}\mathbf{A}_{k+1}\mathbf{G}_{k+1}^{2}\|_{s} \leq c_{7}g(\mathfrak{I}) \|\mathbf{M}_{k}\|_{s}^{\mathfrak{I}_{s}}.$ Hence hold the estimations (3.3), (3.4).

3.1. Theorem of convergence. In the hypothesis I)-II), if $C_{\gamma}+C_{\gamma}<1$, then for every ${}^{\mu}$ >1 there exists ${}^{\gamma}$ 0 depending only ${}^{\mu}$ 0 such that for every ${}^{\gamma}$ >0

i.e. the multigrid algorithm converges, where γ is the solution of the equation

solution which lies in (0,1) interval.

Proof. Let $\{\gamma_k\}$ be the sequence defined by ([3]):

(3.7)
$$\gamma_{1} = \sigma_{3}; \gamma_{k+1} = \sigma_{3} + \delta_{3} \gamma_{k}^{o} + \gamma_{1}$$

Because $\zeta_1 + \delta_1 < 1$, the sequence $\{\gamma_k\}$ is increasing monotone and bounded by the solution of (3.6). Moreover, $f(0) \cdot f(1) < 0$, hence the solution lies in (0,1) interval. From (3.4), there exists such that $\zeta_1 + \delta_1 < 1$ and it is the smallest with this property.

3.2. Remark. For l=1 (V-cycle case) and l=2(W-cycle case) we obtain the following estimations:

(3.8)
$$\gamma^{(M=1)} = 6/(1-5)$$
 and $\gamma^{(M=2)} = (1-\sqrt{1-465})/25$,

where $\Gamma = \Gamma_{\gamma}$, $\delta = \delta_{\gamma}$, of same type as in multigrid literature ([10]).

Comments. By the remarks 1.2 and 1.4, for any variational problem defined by a continuous, elliptic type bilinear functional on a real separable Hilbert space, we can construct an multigrid iterative process such that the bound of the rate of convergence be independent of approximation subspaces, depending only of the continuity and ellipticity constants and of the number of relaxation In the symmetric case the relaxation process is changed by $G_k = I_k - \omega_k A_k$, i.e. by an Richardson process, obtaining same type estimations. We note that we no use the discretization properties for the continuous solution of problem (P) on approximation subspaces.

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