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A NOTE ON THE INVERTIBILITY OF A CLASS IRREDUCIBLE MATRICES

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A note on the invoctibility of a class of

irreducible matrices Popa Constantin

ABSTRACT. M.Kaykobad present in [3]a useful criterion about the invertibility of positive matrices. We prove in this paper a generalization of this criterion for arbitrary irreducible matrices and apply the result on proving the invertibility of matrices which appear in problems of interpolation using Bernstein-Bezier curves ([2]). We obtain also like a corrolary the classical criterion for the invertibility of real irreducible diagonally dominant matrices (see [1], [4]).

1. Notations and definitions.

Let $A = (a_{ij})_{i,j}$, $B = (b_{ij})_{i,j}$ square matrices of order $n \ge 2$ with real elements. We write: $A \ge B$ (resp. $A \ge B$) if $a_{ij} \ge b_{ij}$ (resp. $a_{ij} \ge b_{ij}$) (\forall) i, $j = 1, \ldots, n$; $A \ge 0$ (resp. $A \ge 0$) if $a_{ij} \ge 0$ (resp. $a_{ij} \ge 0$), (\forall) i, $j = 1, \ldots, n$. We use the same notations for vectors $a = (a_i)_i$, $b = (b_i)_i \in \mathbb{R}^n$. By |A| we understand the matrix with elements $|a_{ij}|$, i, $j = 1, \ldots, n$. If $a = (a_i)$, $b = (b_i)$ are two vectors in \mathbb{R}^n we note by $\langle a, b \rangle$ the scalar product of a and b, i.e. $\langle a, b \rangle = \sum_{i=1}^n a_i b_i$.

<u>Definition</u>. A n x n real or complex matrix A is <u>reducible</u> if there is a permutation matrix P such that:

$$P A P^{-1} = \begin{bmatrix} A_{11} & A_{12} \\ 0 & A_{22} \end{bmatrix}$$
 (1).

where All and A22 are square matrices. A matrix A is irreducible if it is not reducible.

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It is well known the following caracterization of irreducible matrices (see for ex. [4], [5]).

Proposition 1. An xn, real or complex matrix $A = (a_{ij})_{ij}$ is irreducible if and only if, for any two distinct indices i, $j \in \{1, ..., n\}$, there is a sequence of nonzero elements of A of the form

$$a_{1,1}, a_{1,1}, a_{2}, \dots, a_{1_m}, j$$
 (2)

Corrolary 1. A is irreducible if and only if A^{T} is irreducible (where A^{T} is the transpose of A).

Definition. A real or complex n x n matrix A = (aij)i,j

is diagonally dominant if:

$$|a_{ii}| \gg \sum_{j \neq i} |a_{ij}|, i = 1, \dots, n$$
 (3)

The matrix is irreducibly diagonally dominant if it is irreducible diagonally dominant and strict inequality holds in (3) for at least one i.

We know the following result

Proposition 2. If A is irreducibly diagonally dominant then A is invertible.

2. The main theorem

In [3]is proved the following

Theorem (partial statement). Suppose that $A = (a_{ij})_{i,j} > 0$,

$$a_{ii} > 0$$
, $i = 1, \dots, n$, $b = (b_i)_i > 0$. If we have:

$$b_1 > \sum_{j \neq i} a_{ij} a_{jj}$$
, $i = 1, ..., n$ (4)

then A is invertible.

We'll make a generalization of this theorem for irreducible matrices with arbitrary real elements. The main result of the paper is

Theorem 1. Let $A = (a_{ij})_{i,j}$ be a real $n \times n$ irreducible matrix, with $a_{ii} \neq 0$, i = 1, ..., n. If a vector $b = (b_i)_i \in \mathbb{R}^n$, b > 0, exist with the property:

$$b_{i} > \sum_{j \neq i} \begin{vmatrix} a_{ij} \\ a_{ij} \end{vmatrix} . b_{j} , (\forall) i = 1, \dots, n$$
 (5)

and strict inequality holds in (5) for at leas one is {1,...,n}, then A is invertible.

Proof. Let $D = \text{diag} \{a_{11}, \dots, a_{nn}\}$, $B = A D^{-1} - I$, $A_{1} = |A|$, $D_{1} = \text{diag} \{|a_{11}|, \dots, |a_{nn}|\}$ and $B_{1} = A_{1}D_{1}^{-1} - I$ (where I is the unit n x n matrix). We have $B_{1} = |B|$. Let $S_{1} = S(B_{1})$ the spectral radius of B_{1} and $C = (I - B_{1}) \cdot b \in \mathbb{R}^{n}$. Accordingly to (5) we have C > 0. A_{1} irreducible implies A_{1}^{T} irreducible (corrolary 1), so B_{1}^{T} is irreducible. But $B_{1}^{T} > 0$, then by Peron-Frobenius theorem ([1], p.195, th.3.5) there exist a vector $\mathbf{d} = (\mathbf{d}_{1})_{1} > 0$ such that $B_{1}^{T} \mathbf{d} = S_{1}^{T} \mathbf{d}$

Then we have

 $\langle \mathbf{d}, \mathbf{c} \rangle = \langle \mathbf{d}, (\mathbf{I} - \mathbf{B}_1) \mathbf{b} \rangle = (\mathbf{I} - \mathbf{S}_1) \langle \mathbf{d}, \mathbf{b} \rangle \rangle \mathbf{0}$ which implies $\mathbf{S}_1 \leq \mathbf{I}$. Let suppose that $\mathbf{S}_1 = \mathbf{I}$. Then $\mathbf{B}_1^T \mathbf{d} = \mathbf{d}$, so $(\mathbf{I} - \mathbf{B}_1)^T \mathbf{d} = \mathbf{0}$ and we have $\mathbf{0} = \langle (\mathbf{I} - \mathbf{B}_1)^T \mathbf{d}, \mathbf{b} \rangle = \langle \mathbf{d}, (\mathbf{I} - \mathbf{B}_1) \mathbf{b} \rangle =$ $= \sum_{i=1}^n \mathbf{d}_i (\mathbf{b}_i - \sum_{j \neq i} \begin{vmatrix} \mathbf{a}_{ij} \\ \mathbf{a}_{jj} \end{vmatrix}, \mathbf{b}_j) \rangle \mathbf{d}_i (\mathbf{b}_i - \sum_{j \neq i} \begin{vmatrix} \mathbf{a}_{ioj} \\ \mathbf{a}_{jj} \end{vmatrix}, \mathbf{b}_j) \rangle \mathbf{0}$

Absurd! (where $i_0 \in \{1, \ldots, n\}$ is an index for which strict inequality holds in (5)). Then $\mathcal{G}(B_1) < 1$. But if $\mathcal{G} = \mathcal{G}(B)$ is the spectral radius of the matrix B we know that ([5], p.lo9): $\mathcal{G}(B) \leq \mathcal{G}(B) = \mathcal{G}(B_1) < 1.$

Then 9 < 1, so I + B is invertible ([5], p.26). But I + B = AD⁻¹ by the definition of matrix B, so that A is invertible. \square We may obtain the "transpose" statement of the theorem 1.

Corrolary 2. Let $A = (a_{ij})_{i,j}$ be a real n x n irreducible matrix with $a_{ii} \neq 0$, i = 1, ..., n. If a vector $b = (b_i)_i \in \mathbb{R}^n$, b > 0,

exist with the property: $b_{i} \gg \frac{2}{J^{2}} \left(\begin{array}{c} a_{ij} \\ a_{ij} \end{array} \right) b_{j} = 1, \dots, n \qquad (6)$

and strict inequality holds in (6) for at least one i $\in \{1, \dots, n\}$, then A is invertible:

We have also

Corrolary 3. If A is a real n x n matrix with a i f o, i = 1,..., n such that A or A^T is irreducibly diagonally dominant, then A is invertible.

Proof. We apply theorem 1 for the matrix $C = \frac{a_{1,1}}{a_{1,1}}$ and the vector $b \in \mathbb{R}^n$, $b = (1,1,...,1) \cdot \mathbb{Z}$

Remarks.

- a) Corrolary 3 is exactly proposition 2 for the case of real matrices.
- b) The condition in theorem 1 about the existence of an index $i_0 \in \{1, ..., n\}$ such that (5) holds strictly is realy necessary. Indeed for the matrix.

$$A = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & 0 & 0 \\ \frac{1}{4} & \frac{1}{2} & \frac{1}{4} & 0 \\ 0 & \frac{1}{4} & \frac{1}{2} & \frac{1}{4} \\ 0 & 0 & \frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

which is not invertible $(Ax_0 = 0, \text{ where } x_0 = (1,-1,1,-1))$ we'll prove that (\forall) b = $(b_i)_i \in \mathbb{R}^4$, b > 0 such that (5) holds, then none of these inequalities cannot be strict.

Indeed, if b satisfies (5) it is easy to see that $b_1 = b_2 = b_3 = b_4 = 0$ on Then if we suppose that one of the

inequalities from (5) is strictly satisfied for example with $i = i_0$ we'll have:

$$\alpha > \sum_{j \neq i_0} 2 a_{i_0 j} d = 2 \alpha \sum_{j \neq i_0} a_{i_0 j} = 2 \alpha \frac{1}{2} = \alpha$$
 Absurdi

3. Application.

Let $n \geqslant 2$ and u_0 , u_1, \ldots, u_n , $\lambda_1, \ldots, \lambda_n \in (0,1)$ be arbitrary constants. We consider the following matrices of order n+1:

$$A = \begin{bmatrix} b_0 & c_0 & 0 & 0 & \dots & 0 & 0 \\ a_1 & b_1 & c_1 & 0 & \dots & 0 & 0 \\ 0 & a_2 & b_2 & c_2 & 0 & \dots & 0 & 0 \\ 0 & \dots \\ 0 & \dots \\ 0 & \dots \\ b_0^* & c_0^* & 0 & 0 & \dots & \dots & \dots & \dots & \dots \\ a_1^* & b_1^* & c_1^* & 0 & \dots & \dots & \dots & \dots & \dots \\ 0 & a_2^* & b_2^* & c_2^* & 0 & \dots & \dots & \dots & \dots \\ 0 & a_2^* & b_2^* & c_2^* & 0 & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & \dots \\ 0 & 0 & \dots \\ 0 & 0 & 0 & \dots \\ 0 & \dots \\ 0 & 0 & \dots \\ 0 & 0 & \dots \\ 0 & \dots \\ 0 & 0 & \dots \\ 0 & \dots \\ 0 & \dots \\ 0 & \dots$$

where

$$a_0 = 0$$
 ; $c_0 = \lambda_1$
 $a_n = 1 - \lambda_n$; $c_n = 0$
 $a_i = (1 - \lambda_i)(1 - u_i)^2$; $c_i = u_i^2 \lambda_{i+1}$, $i = 1, ..., n-1$
 $b_i = 1 - (a_i + c_i)$, $i = 0, ..., n$

and

$$a_{0}^{i} = (1 - \lambda_{n+1}) (1 - u_{0})^{2}; \quad c_{0}^{1} = u_{0}^{2} \lambda_{1}$$
 $a_{1}^{i} = (1 - \lambda_{1})(1 - u_{1})^{2}; \quad c_{1}^{i} = u_{1}^{2} \lambda_{1+1}, \quad 1 = 1, ..., n$
 $b_{1} = 1 - (a_{1}^{i} + c_{1}^{i}), \quad 1 = 0, ..., n^{n}$

These matrices appear in problems concerning the interpolation with Bernstein-Bezier curves (see for ex. [2]). Using theorem l we'll prove that A and B are invertible so that the interpolation problem has unique solution.

For example for matrix A we'll put

$$\beta_{i} = \delta_{i} \cdot b_{i} \cdot i = 0, ..., n$$
 (7)

where T; are positive numbers which satisfies:

We then have $\beta_{i} > 0$ i = 0, ..., n and: $\beta_{1} \frac{\lambda_{1}}{b_{1}} = \gamma_{1} \cdot b_{1} \cdot \frac{\lambda_{1}}{b_{1}} = \gamma_{1} \cdot \lambda_{1} = \gamma_{0} \cdot (1 - \lambda_{1}) = \gamma_{0} \cdot b_{0} = \beta_{0}$ $\beta_{1} \frac{\lambda_{1}}{b_{1}} = \gamma_{1} \cdot b_{1} \cdot \frac{\lambda_{1}}{b_{1}} = \gamma_{1} \cdot \lambda_{1} = \gamma_{0} \cdot (1 - \lambda_{1}) = \gamma_{0} \cdot b_{0} = \beta_{0}$ $\beta_{1} \frac{\lambda_{1}}{b_{1}} = \gamma_{1} \cdot b_{1} \cdot \frac{\lambda_{1}}{b_{1}} = \gamma_{1} \cdot \lambda_{1} = \gamma_{1} \cdot \frac{\lambda_{1}}{b_{1}} = \gamma_{1} \cdot \frac{\lambda_{1$

=
$$\beta_{i+1} - 2 \beta_{i+1} u_{i+1} (1 - u_{i+1}) < \beta_{i+1}$$
, $i = 0, ..., n-2$

and $\beta_{n-1} \cdot \frac{1-\lambda_n}{b_{n-1}} = \gamma_{n-1}(1-\lambda_n) = \gamma_n \lambda_n = \gamma_n b_n = \beta_n$

So the matrix A (which is irreducible, [5] pag.lo5) and the vector $\beta = (\beta_0, \dots, \beta_n)$ defined in (7)-(8) verifies conditions of theorem 1. Then A is invertible. For the matrix

we observe first that the associated graph is strongly connected so B is irreducible (see [5], p.105, 6.2.4). Then using the same vector $\beta = (\beta_0, \dots, \beta_n)$ like for the matrix A we obtain, using theorem 1, that also B is invertible.

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